

Übung 10 – BDDs & symbolic model checking

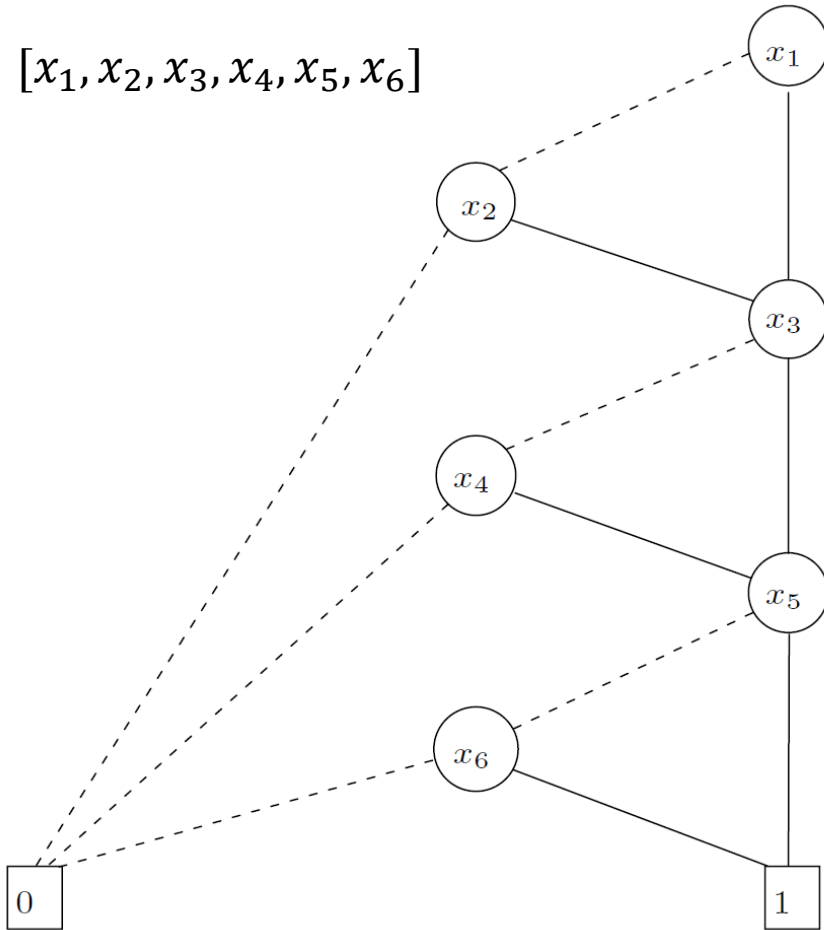
Formale Techniken in der Software-Entwicklung

Christian Kroiß

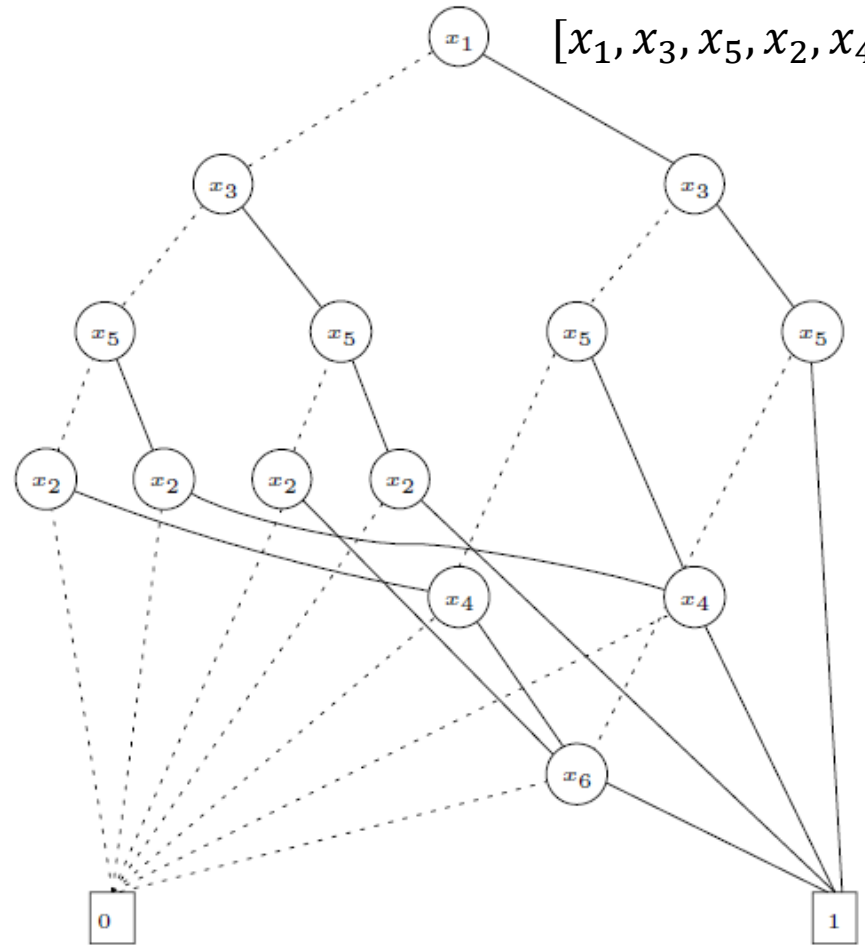


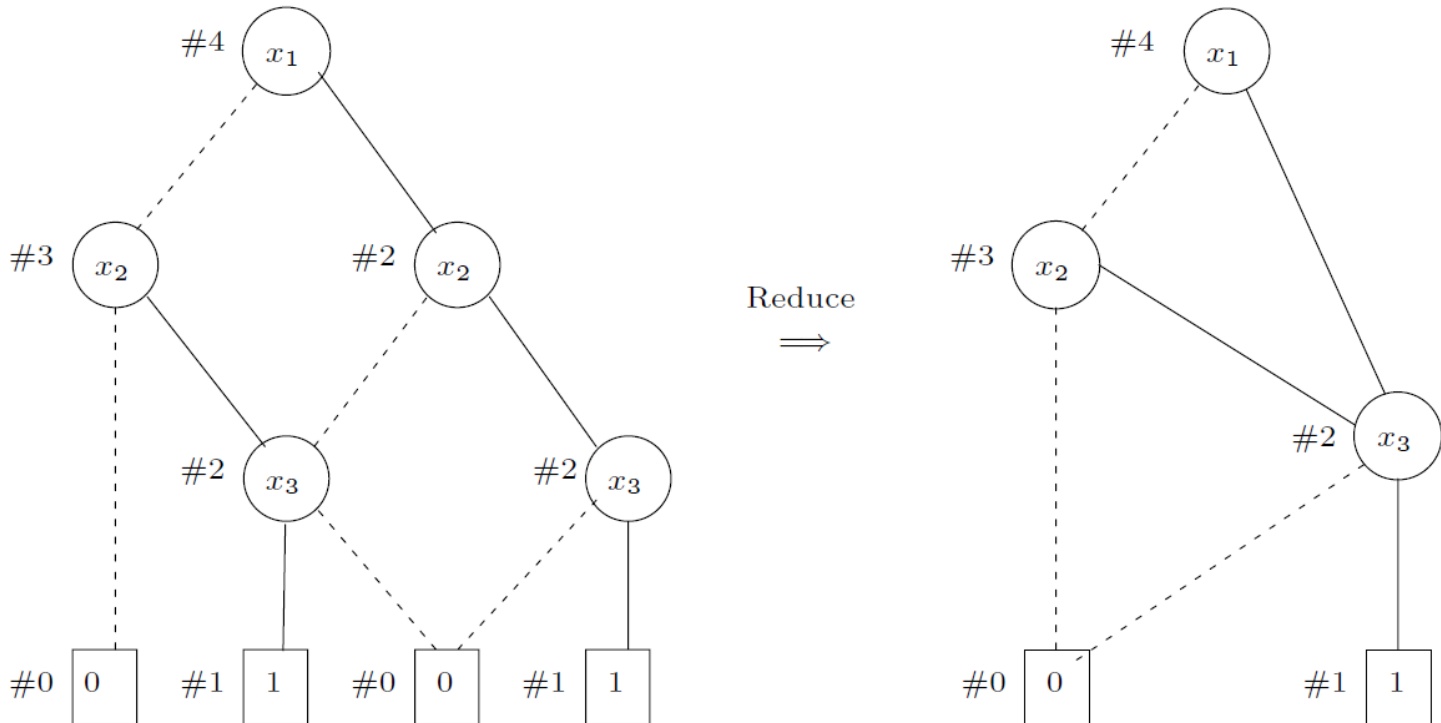
$$(x_1 \vee x_2) \wedge (x_3 \vee x_4) \wedge (x_5 \vee x_6)$$

$[x_1, x_2, x_3, x_4, x_5, x_6]$

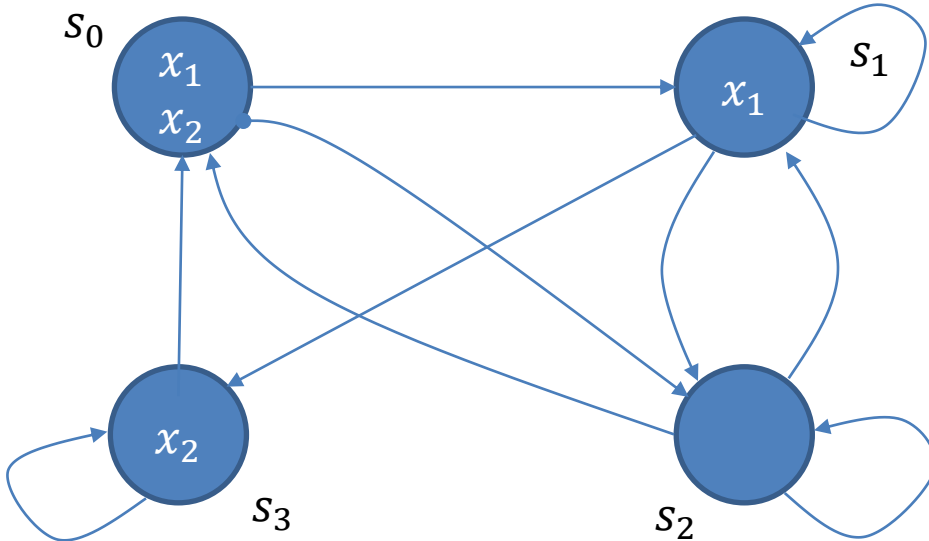


$[x_1, x_3, x_5, x_2, x_4, x_6]$





- If the label $\text{id}(\text{lo}(n))$ is the same as $\text{id}(\text{hi}(n))$, then we set $\text{id}(n)$ to be that label. In other words, node n performs a redundant test and can be eliminated by reduction C2.
- If there is another node m such that n and m have the same variable x_i , and $\text{id}(\text{lo}(n)) = \text{id}(\text{lo}(m))$ and $\text{id}(\text{hi}(n)) = \text{id}(\text{hi}(m))$, then we set $\text{id}(n)$ to be $\text{id}(m)$. This is because the nodes n and m compute the same boolean function (compare with reduction C3).
- Otherwise, we set $\text{id}(n)$ to the next unused integer label.



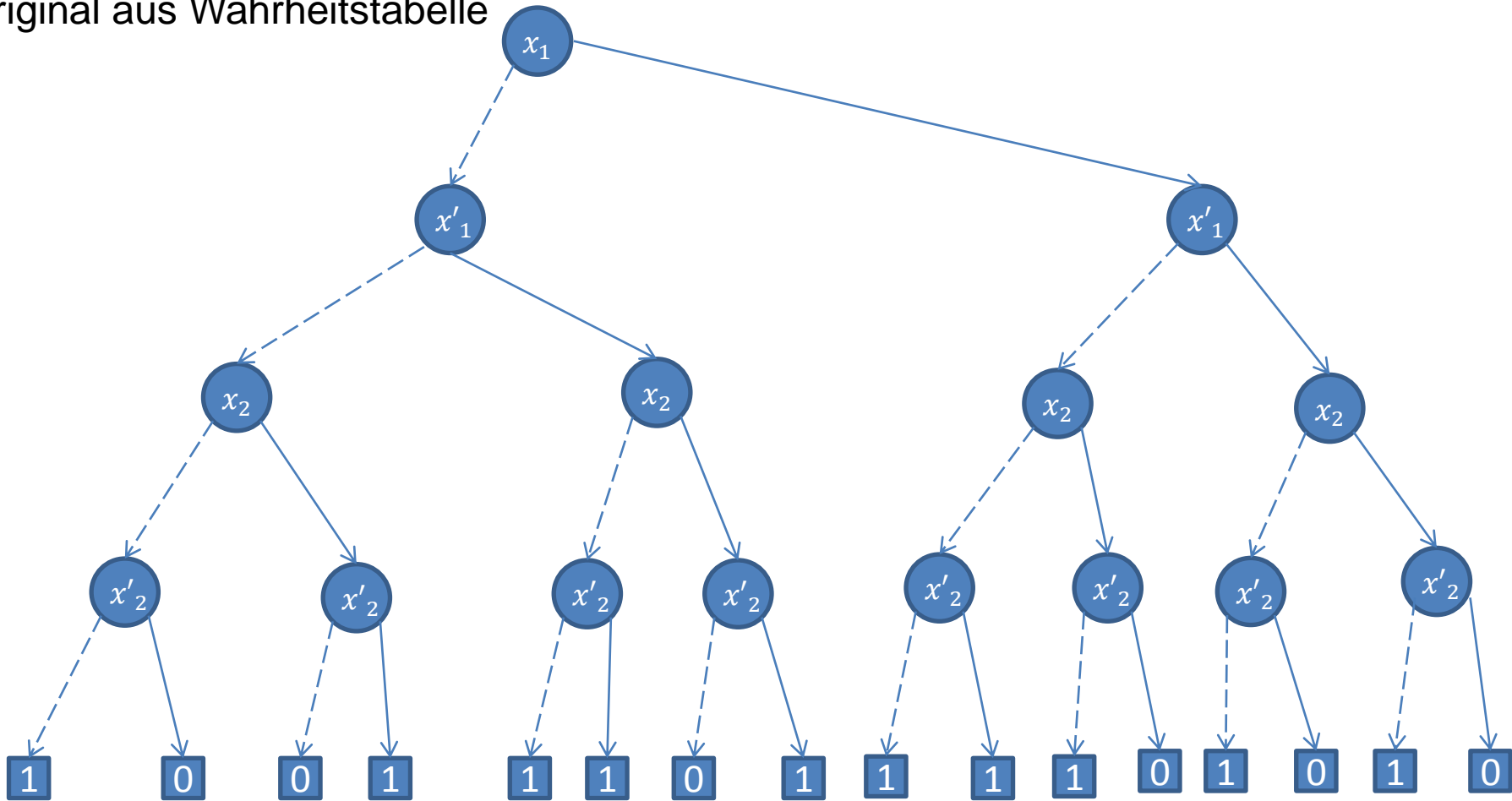
- Work out the truth table for the transition relation, ordering the columns $[x_1, x_1', x_2, x_2']$. There should be as many 1s in the final column as there are arrows in the transition relation.
- Draw the OBDD (ordered BDD) for this transition relation using the variable ordering $[x_1, x_1', x_2, x_2']$.



X1	X1'	X2	X2'	→	
0	0	0	0	1	s2→s2
0	0	0	1	0	s2→s3
0	0	1	0	0	s3→s2
0	0	1	1	1	s3→s3
0	1	0	0	1	s2→s1
0	1	0	1	1	s2→s0
0	1	1	0	0	s3→s1
0	1	1	1	1	s3→s0
1	0	0	0	1	s1→s2
1	0	0	1	1	s1→s3
1	0	1	0	1	s0→s2
1	0	1	1	0	s0→s3
1	1	0	0	1	s1→s1
1	1	0	1	0	s1→s0
1	1	1	0	1	s0→s1
1	1	1	1	0	s0→s0

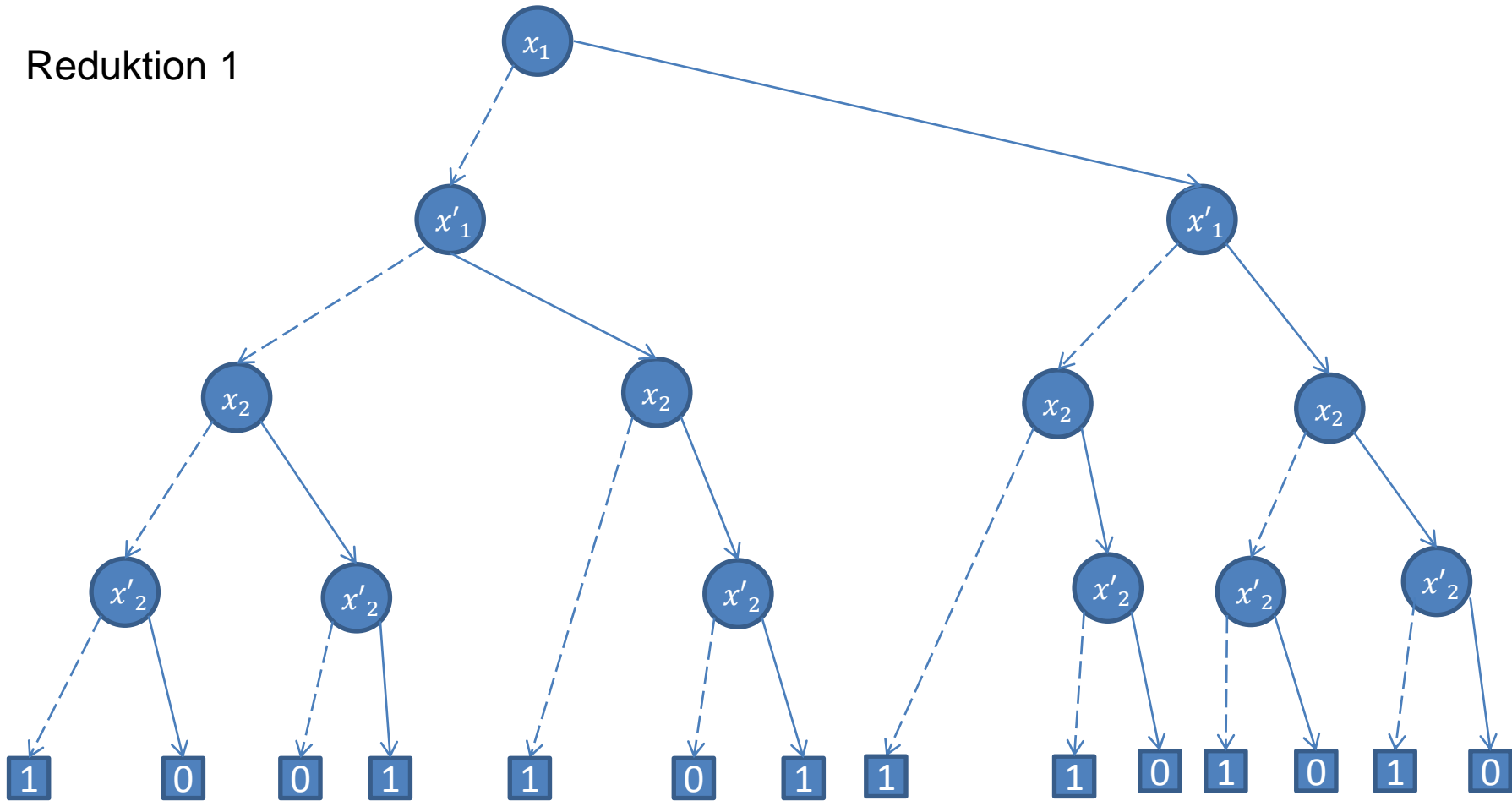


Original aus Wahrheitstabelle



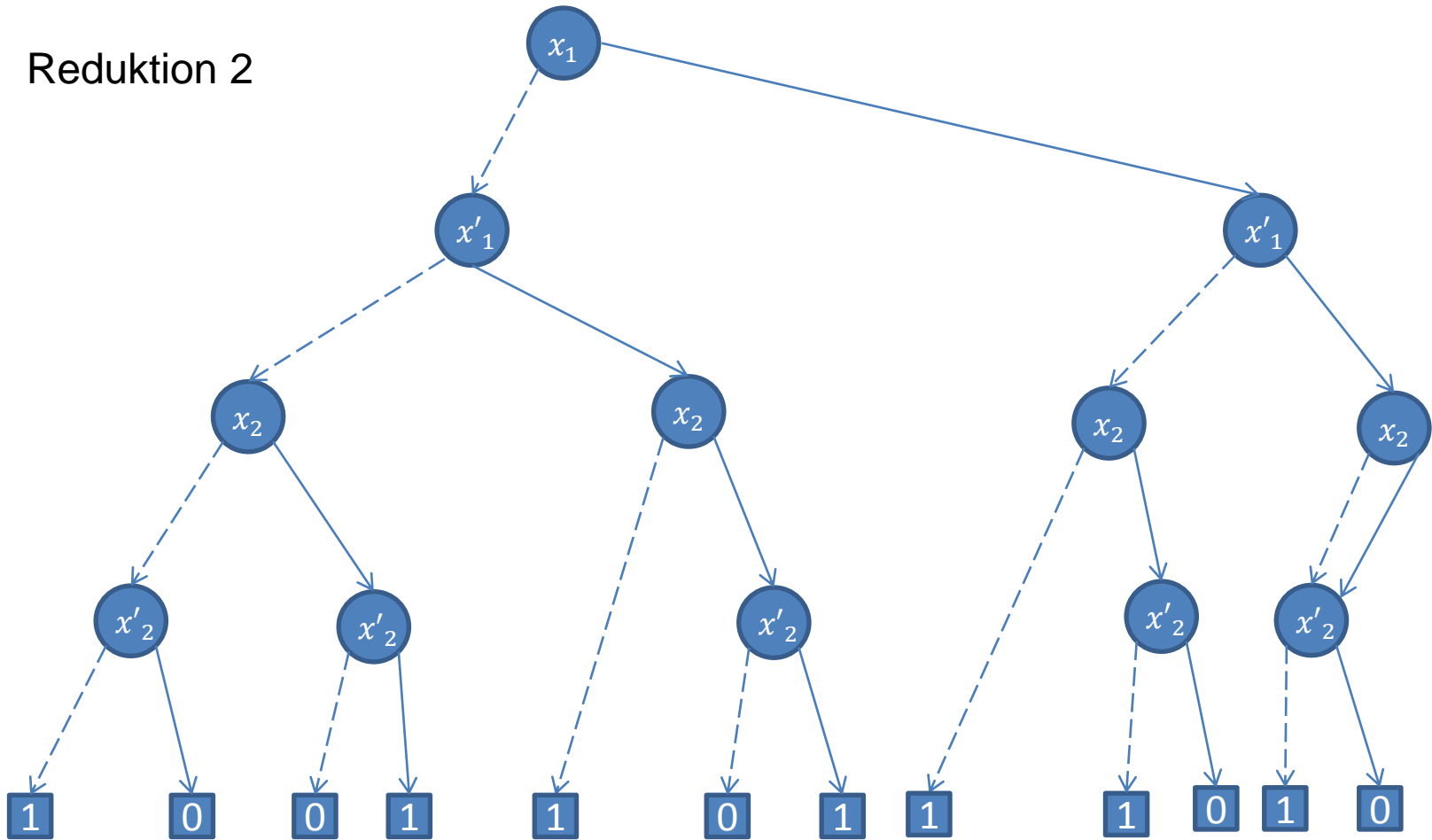


Reduktion 1



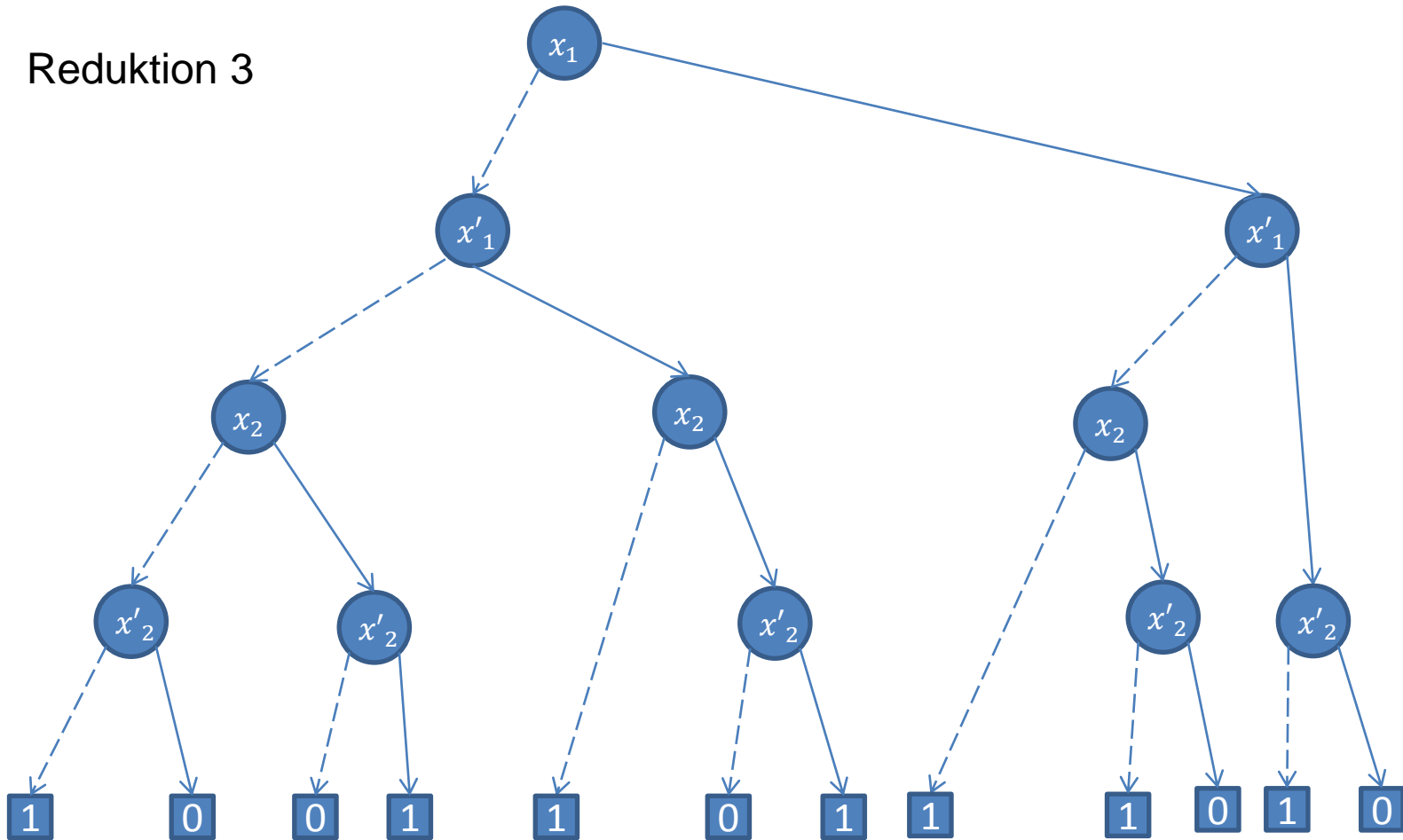


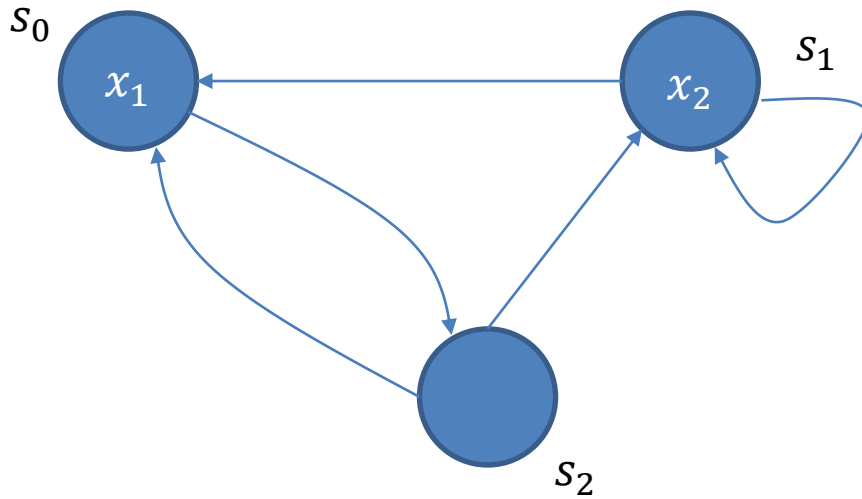
Reduktion 2





Reduktion 3





Apply the CTL model checking algorithm, but now interpreted over OBDDs in the ordering $[x_1, x_2]$, to compute the set of states of the model above which satisfy

$$AG (x_1 \vee \neg x_2)$$

Show the BDDs which are computed along the way.

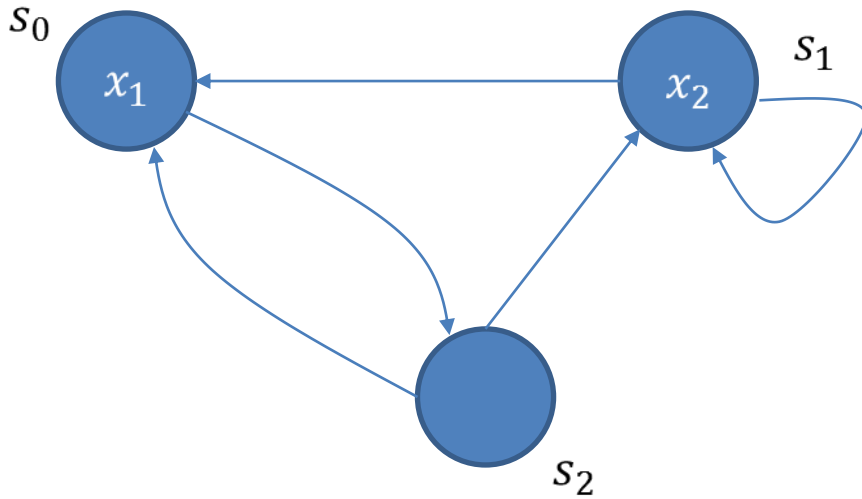


Umformung:

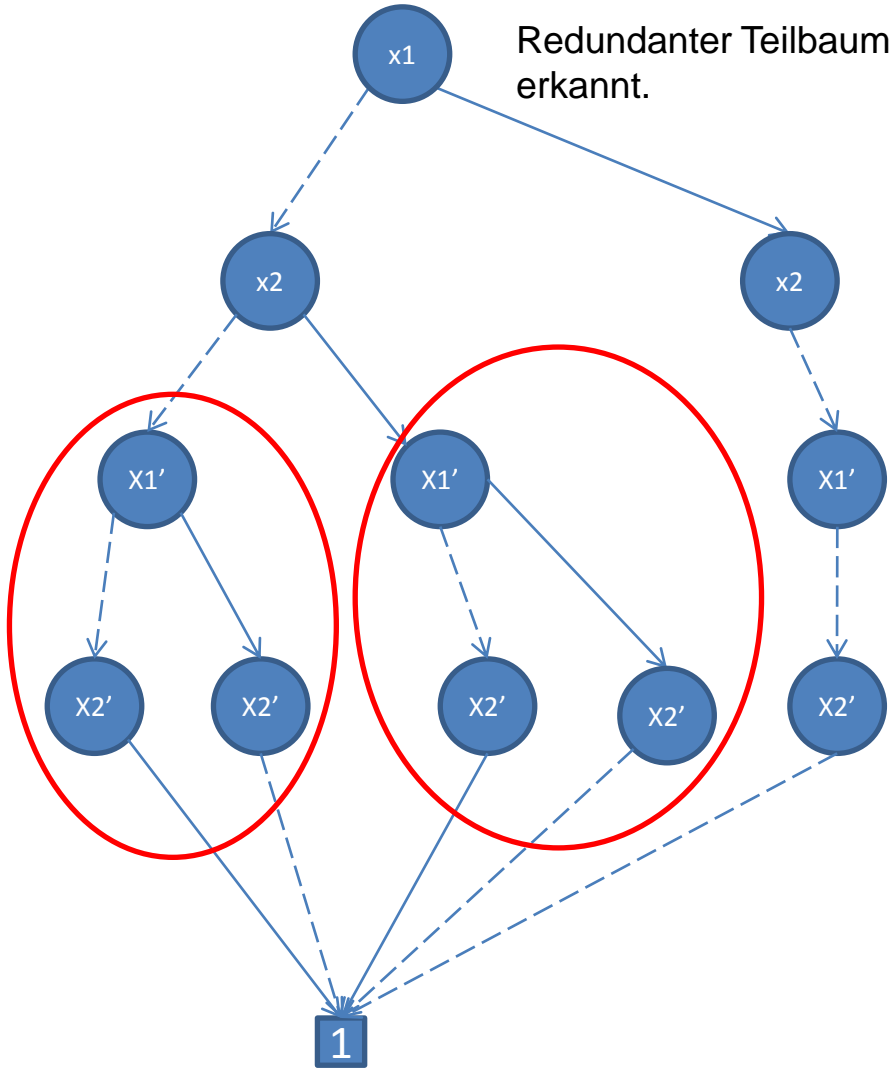
$$\begin{aligned} AG(x_1 \vee \neg x_2) &= \neg EF \neg(x_1 \vee \neg x_2) \\ &= \neg(\text{true } EU (\neg x_1 \wedge x_2)) \end{aligned}$$

$$\varphi := \neg x_1 \wedge x_2$$

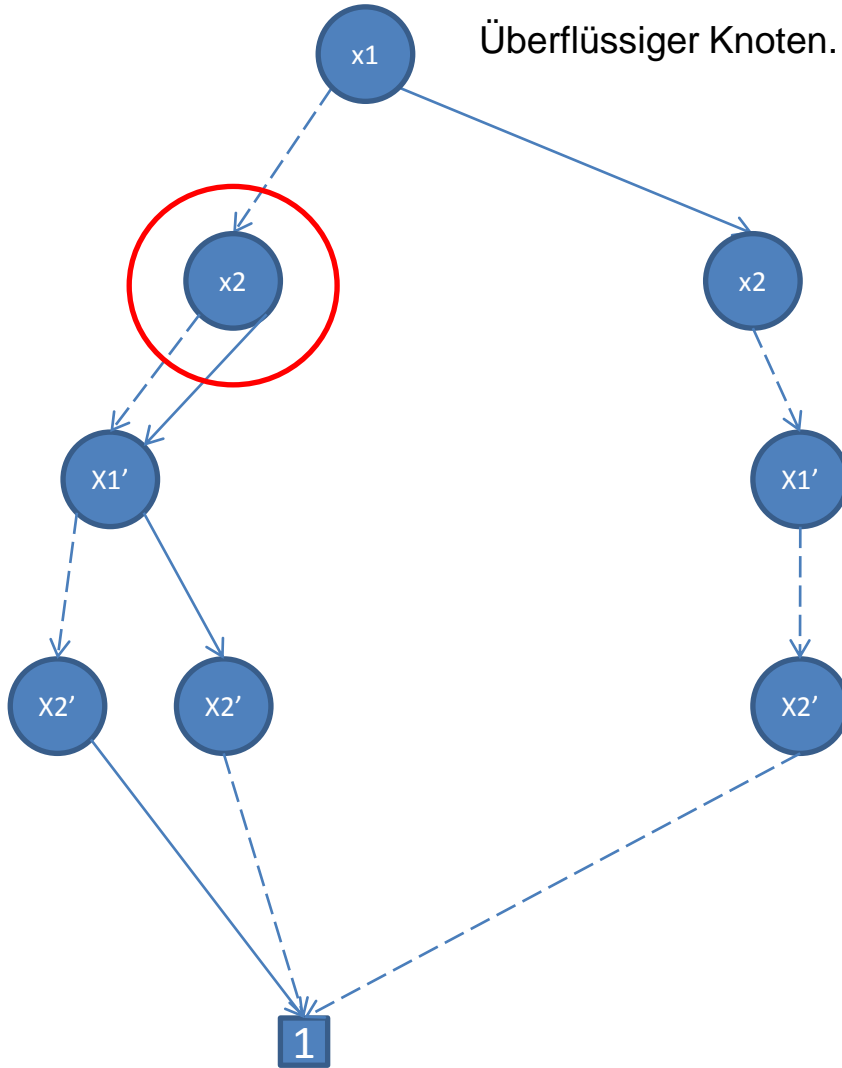
$\llbracket \text{true } EU \varphi \rrbracket$ kleinster Fixpunkt von $\pi : Z \mapsto \llbracket \varphi \rrbracket \cup R^{-1}(Z)$



X1	X2	X1'	X2'	→	
0	0	0	0	0	s2→s2
0	0	0	1	1	s2→s1
0	1	0	0	0	s1→s2
0	1	0	1	1	s1→s1
0	0	1	0	1	s2→s0
0	0	1	1	0	-
0	1	1	0	1	s2→s0
0	1	1	1	0	-
1	0	0	0	1	s0→s2
1	0	0	1	0	s0→s1
1	1	0	0	0	-
1	1	0	1	0	-
1	0	1	0	0	s0→s0
1	0	1	1	0	-
1	1	1	0	0	-
1	1	1	1	0	-



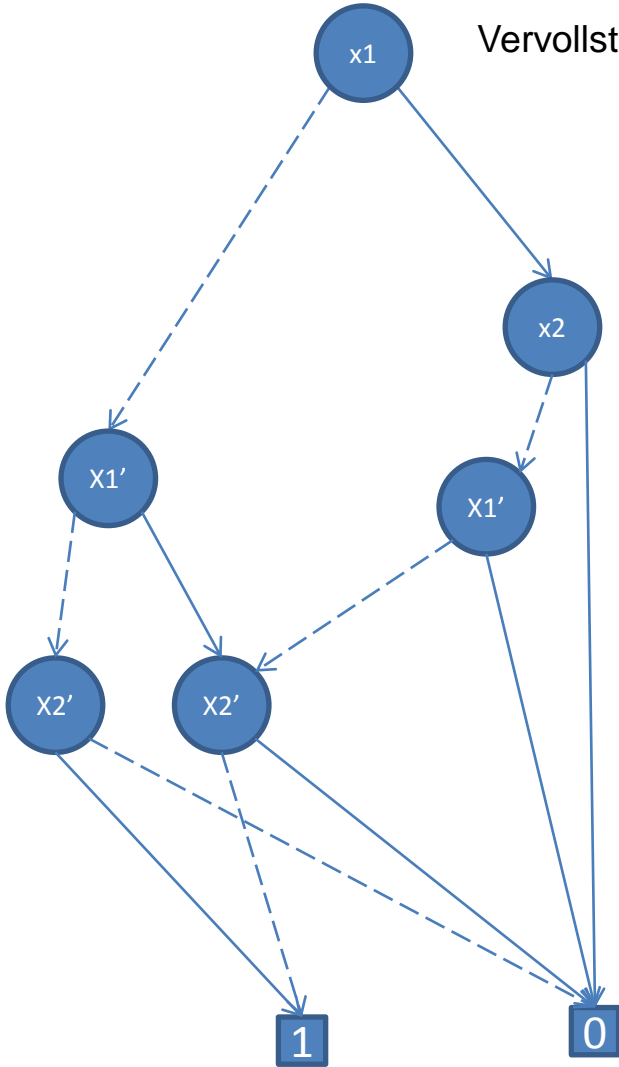
X1	X2	X1'	X2'	→	
0	0	0	0	0	s2→s2
0	0	0	1	1	s2→s1
0	1	0	0	0	s1→s2
0	1	0	1	1	s1→s1
0	0	1	0	1	s2→s0
0	0	1	1	0	-
0	1	1	0	1	s2→s0
0	1	1	1	0	-
1	0	0	0	1	s0→s2
1	0	0	1	0	s0→s1
1	1	0	0	0	-
1	1	0	1	0	-
1	0	1	0	0	s0→s0
1	0	1	1	0	-
1	1	1	0	0	-
1	1	1	1	0	-



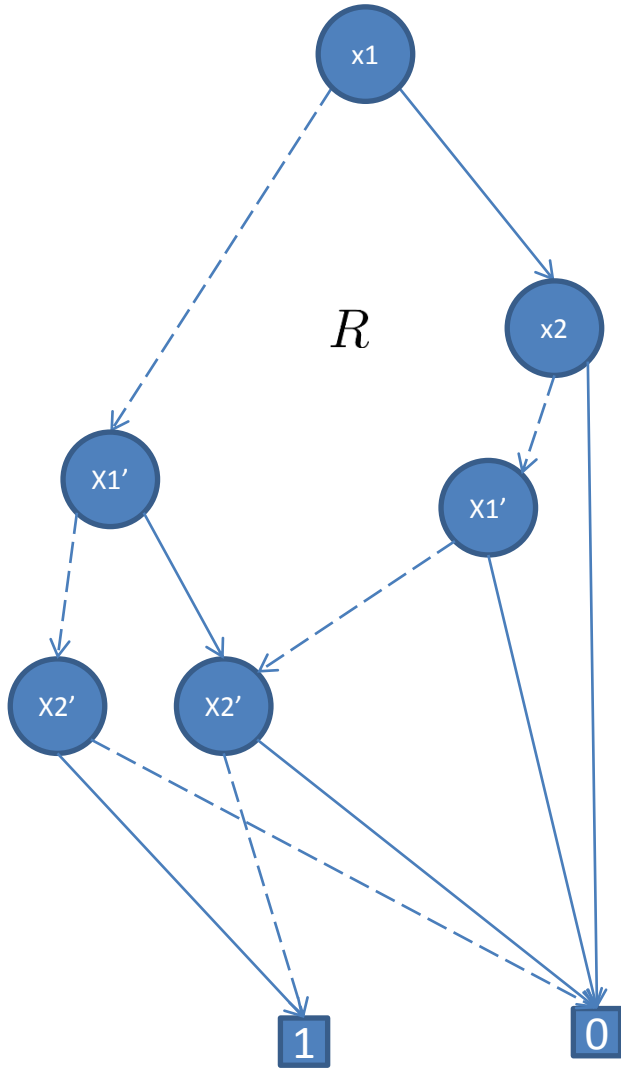
X1	X2	X1'	X2'	→	
0	0	0	0	0	s2→s2
0	0	0	1	1	s2→s1
0	1	0	0	0	s1→s2
0	1	0	1	1	s1→s1
0	0	1	0	1	s2→s0
0	0	1	1	0	-
0	1	1	0	1	s2→s0
0	1	1	1	0	-
1	0	0	0	1	s0→s2
1	0	0	1	0	s0→s1
1	1	0	0	0	-
1	1	0	1	0	-
1	0	1	0	0	s0→s0
1	0	1	1	0	-
1	1	1	0	0	-
1	1	1	1	0	-



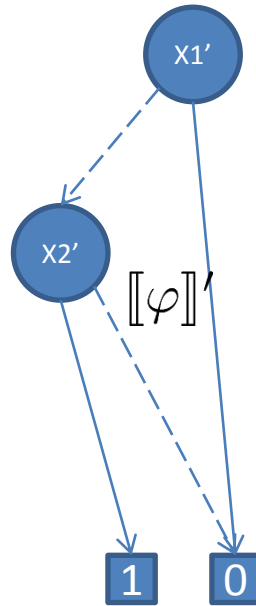
Vervollständigen



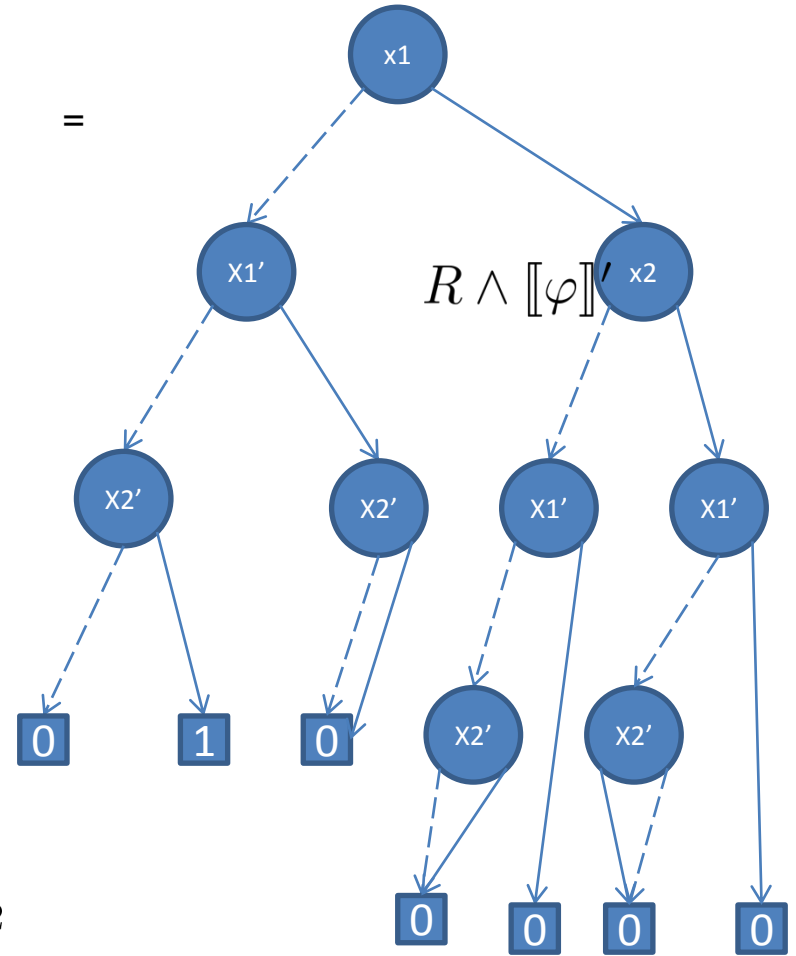
X1	X2	X1'	X2'	→	
0	0	0	0	0	s2→s2
0	0	0	1	1	s2→s1
0	1	0	0	0	s1→s2
0	1	0	1	1	s1→s1
0	0	1	0	1	s2→s0
0	0	1	1	0	-
0	1	1	0	1	s2→s0
0	1	1	1	0	-
1	0	0	0	1	s0→s2
1	0	0	1	0	s0→s1
1	1	0	0	0	-
1	1	0	1	0	-
1	0	1	0	0	s0→s0
1	0	1	1	0	-
1	1	1	0	0	-
1	1	1	1	0	-



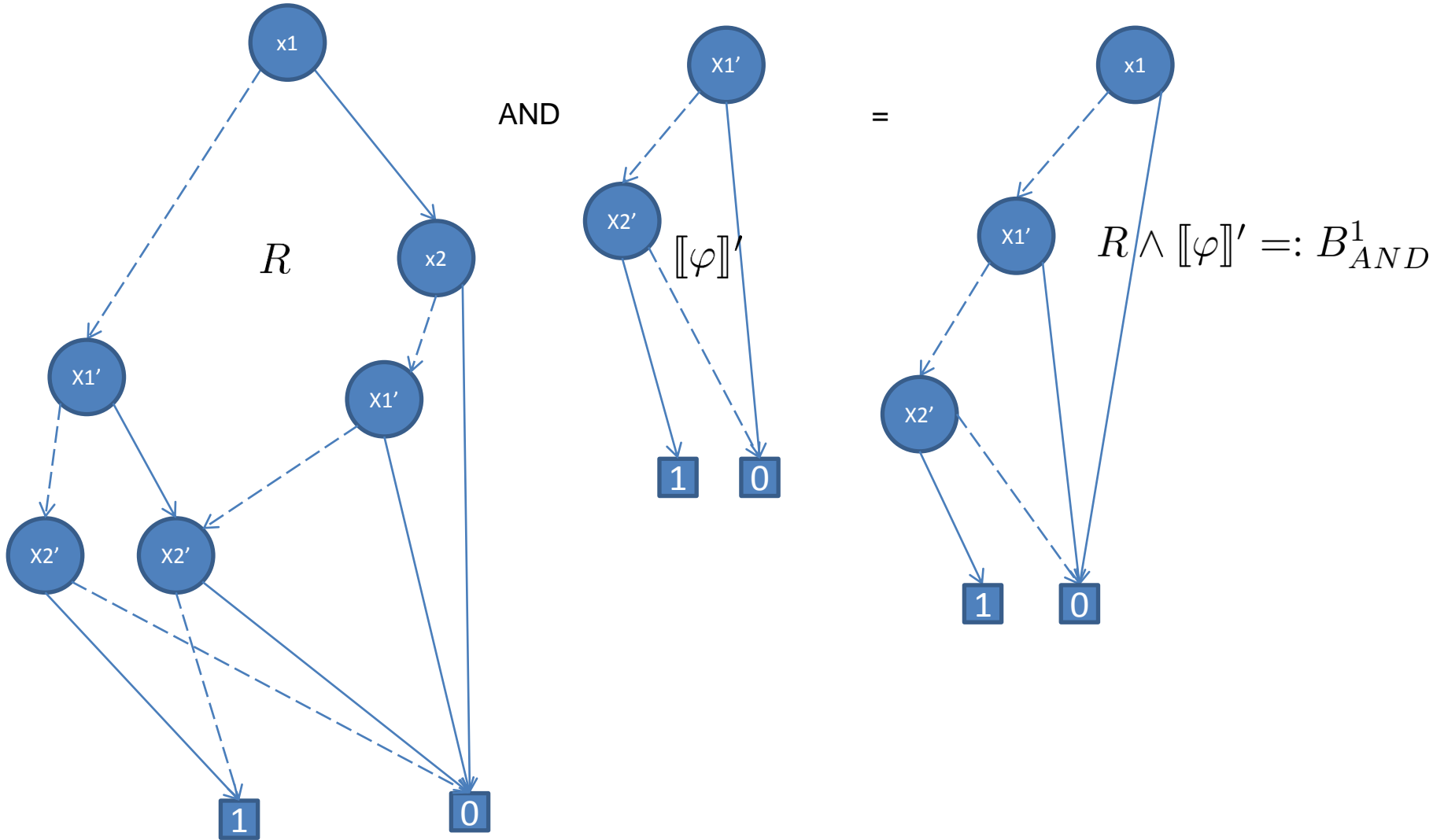
AND

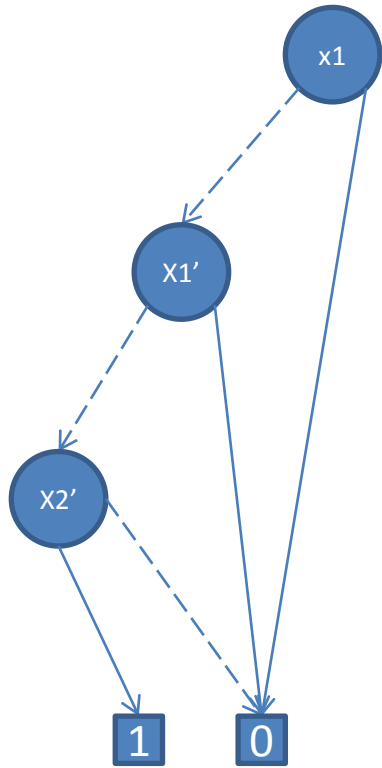


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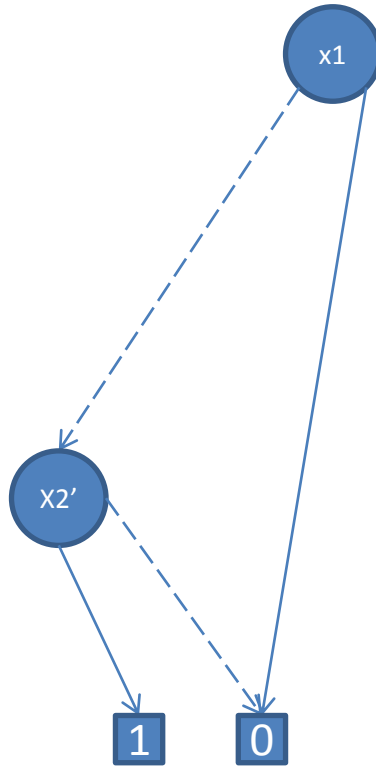


$$\varphi = x_1 \vee \neg x_2$$





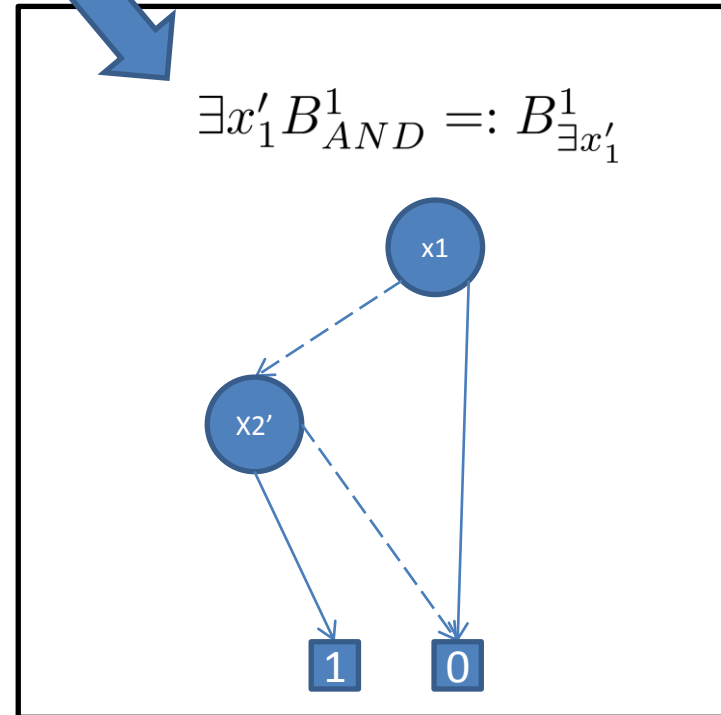
$$B_{AND}^1 | x'_1 = false$$



$$B_{AND}^1 | x'_1 = false$$

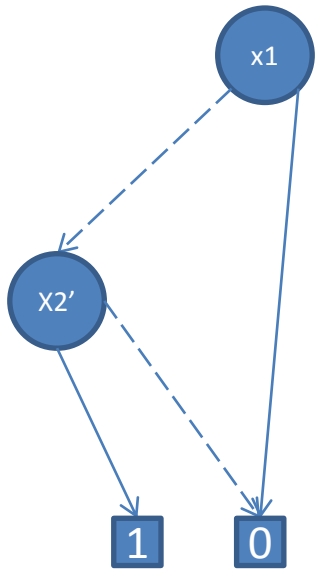
OR

0





$$B_{\exists x'_1}^1$$

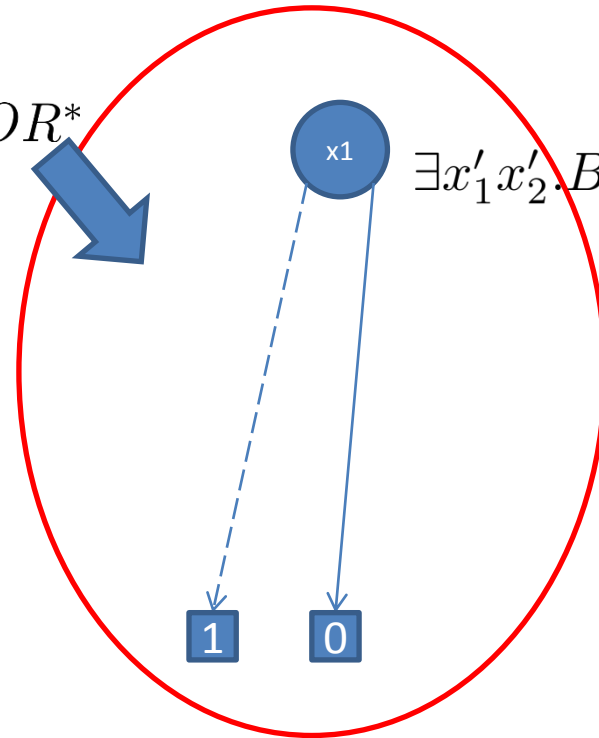


$$B_{\exists x'_1}^1 | x'_2 = false$$

0

$$B_{\exists x'_1}^1 | x'_2 = true$$

OR*



$$\exists x'_1 x'_2 . B_{AND}^1 =: R^{-1}$$

*(OR 0 doesn't change anything)

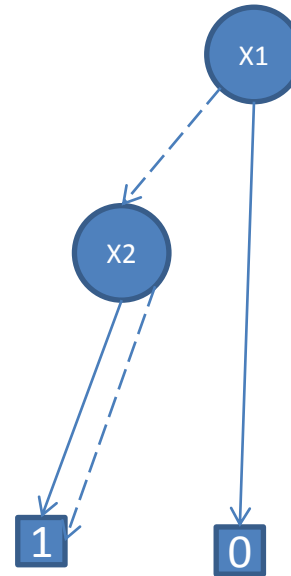
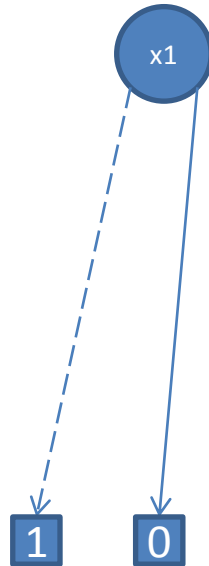
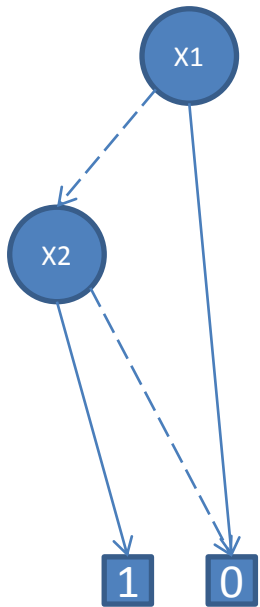


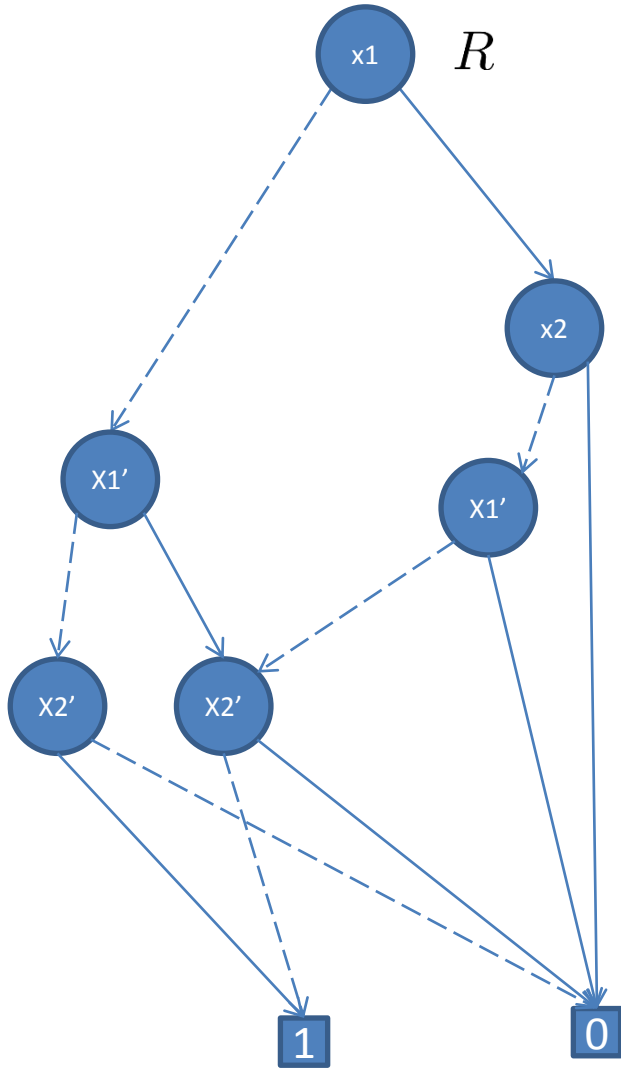
$[\varphi]$

\cup

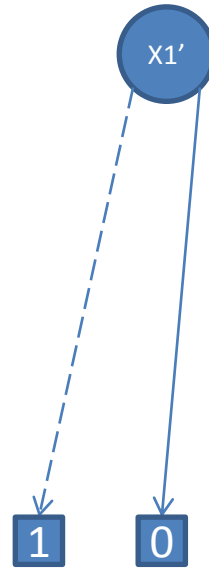
$R^{-1}(Z)$

$:= \pi^2(Z)$

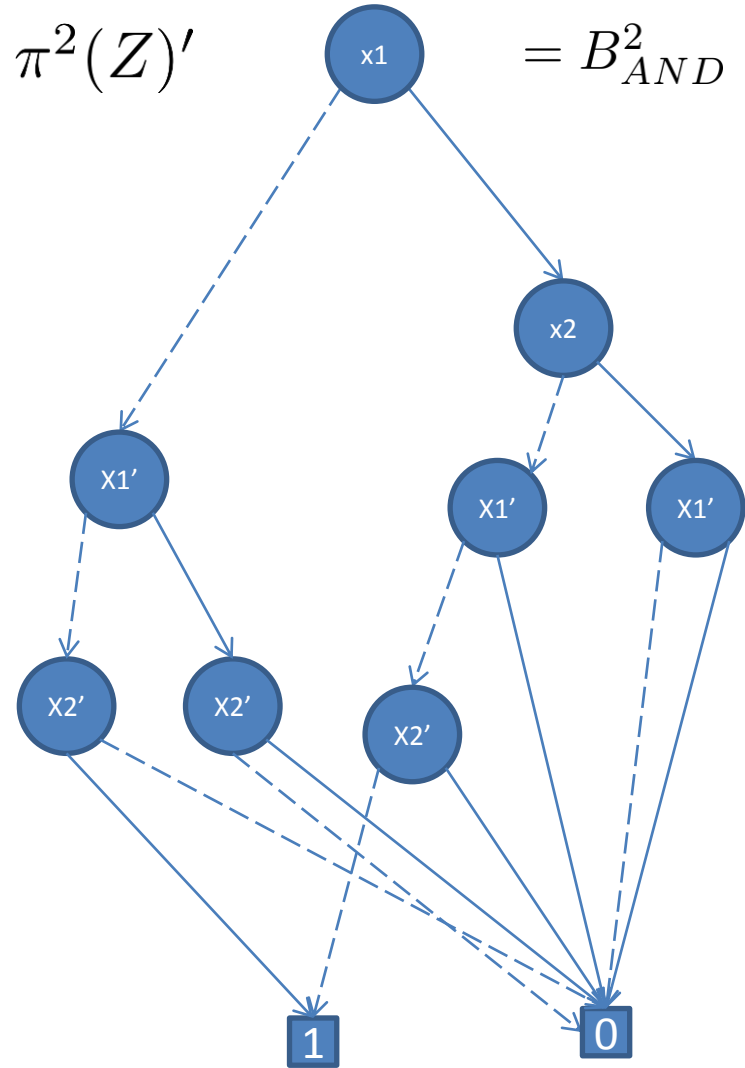




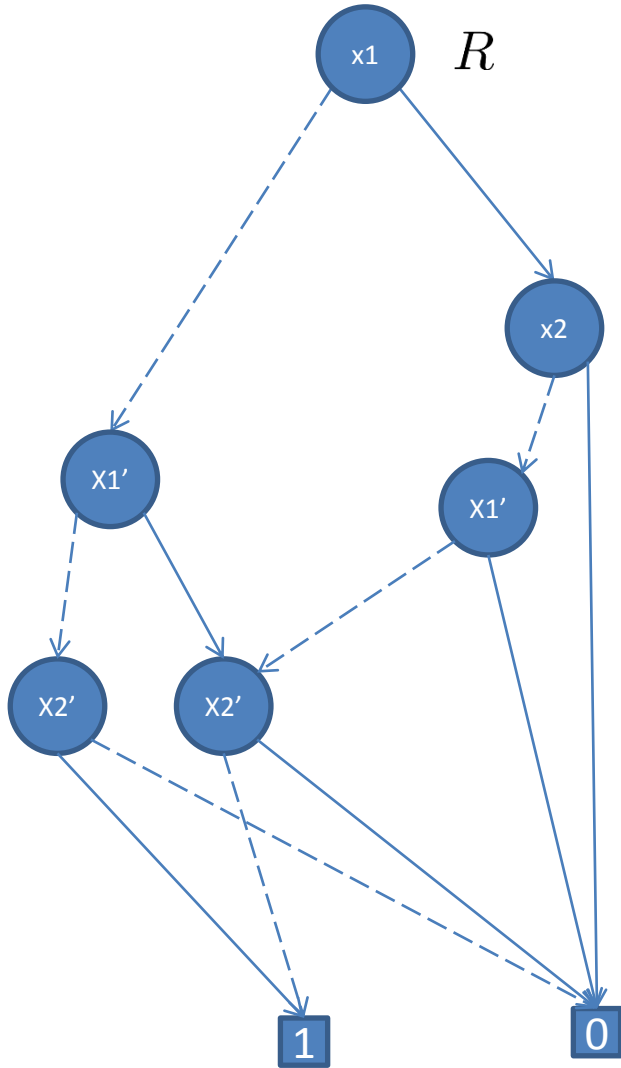
AND



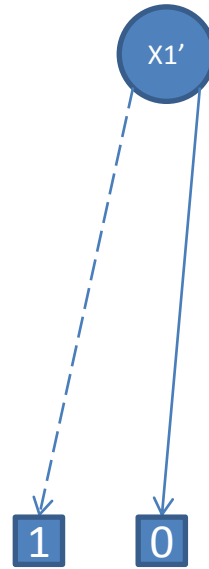
$= B_{AND}^2$



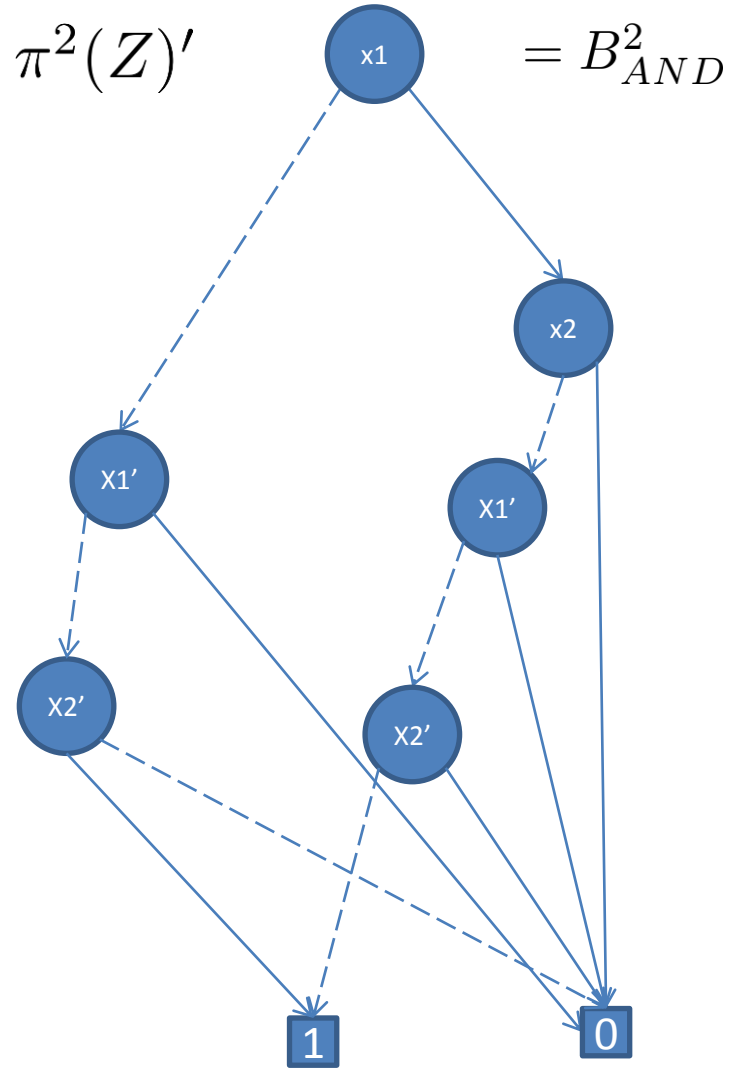
2. Rekursion

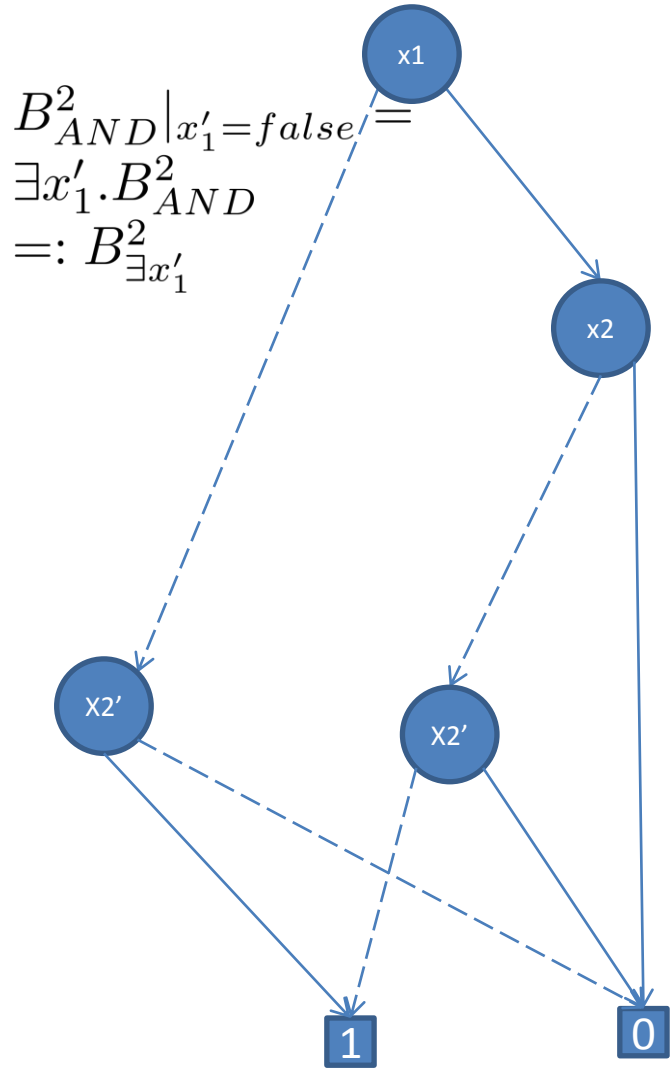


AND



$\pi^2(Z)'$



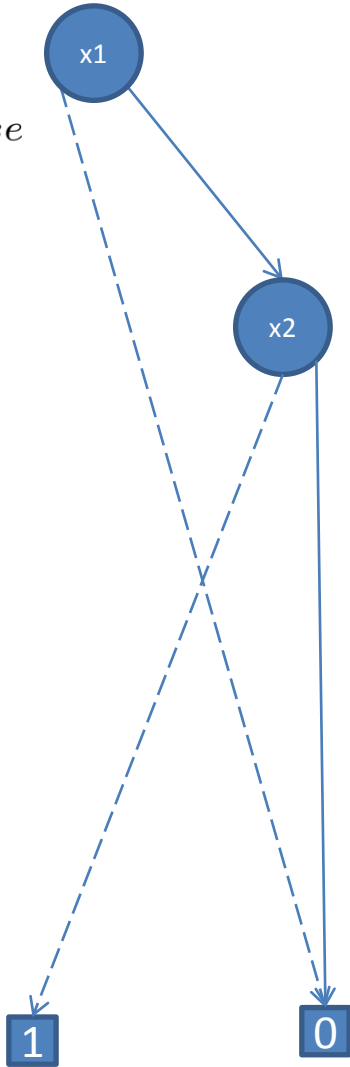


$$B_{AND}^2 | x'_1 = true$$

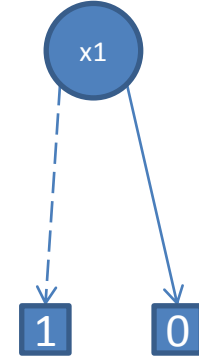
0



$$B_{\exists x'_1}^2 \mid x'_2 = false$$



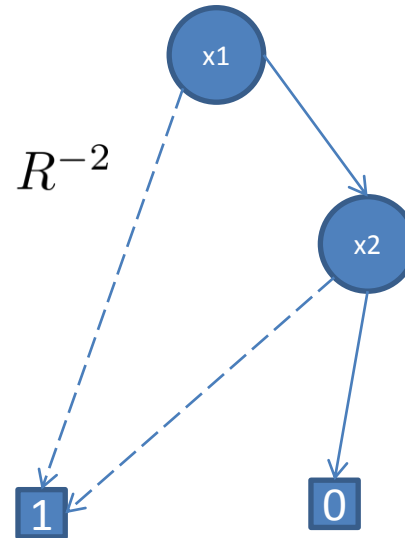
$$B_{\exists x'_1}^2 \mid x'_2 = true$$



OR



$$\exists x'_1 x'_2. B_{AND}^2 =: R^{-2}$$





AND SO ON...

Man überprüft z.B. leicht, dass R^{-1} gerade die Vorgänger der States beschreibt, die im ersten Schritt die Formel φ erfüllen:

$$\varphi := \neg x_1 \wedge x_2$$

$$\llbracket \varphi \rrbracket = \{s_1\}$$

$$R^{-1}(\llbracket \varphi \rrbracket) = \llbracket \neg x_1 \rrbracket = \{s_2, s_1\}$$



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