

Formale Spezifikation und Verifikation

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Hennessy-Milner Logic

Verifying Correctness of Reactive Systems

Let *Impl* be an implementation of a system (e.g., in CCS syntax).

Equivalence Checking Approach

$$\textcolor{red}{Impl} \equiv \textcolor{red}{Spec}$$

- \equiv is an abstract equivalence, e.g. \sim or \approx
- *Spec* is often expressed in the same language as *Impl*
- *Spec* provides the full specification of the intended behaviour
- Implementation verification requires the full description of both models. . .
- . . . and the derivation of the respective state spaces.
- Some specifications may seem unnatural. . .

Model Checking Approach

Model Checking Approach

$$\textit{Impl} \models \textit{Property}$$

- \models is the satisfaction relation
- *Property* is a particular feature, often expressed via a logic
- *Property* is a partial specification of the intended behaviour

Our Aim

Develop a logic in which we can express interesting properties of reactive systems.

Logical Properties of Reactive Systems

Modal Properties — what can happen **now** (possibility, necessity)

- drink a coffee (can drink a coffee now)
- does not drink tea
- drinks both tea and coffee
- drinks tea after coffee

Temporal Properties — behaviour in **time**

- never drinks any alcohol
(**safety property**: nothing bad can happen)
- eventually will have a glass of wine
(**liveness property**: something good will happen)

Can these properties be expressed using equivalence checking?

Syntax ($a \in Act$)

$$F, G ::= tt \mid ff \mid F \wedge G \mid F \vee G \mid \langle a \rangle F \mid [a]F$$

tt all processes satisfy this property

ff no process satisfies this property

\wedge, \vee usual logical AND and OR connectives

$\langle a \rangle F$ (**possibility**) asserts (of a given P): It is possible for P to perform an action a and evolve into a Q that satisfies F — there is at least one a -successor that satisfies F

$[a]F$ (**necessity**) asserts (of a given P): If P can perform an action a then it must evolve into a Q that satisfies F — all a -successors have to satisfy F

Hennessy-Milner Logic — Semantics

Let $(Proc, Act, \{\xrightarrow{a} \mid a \in Act\})$ be an LTS.

Satisfaction relation $p \models F$ ($p \in Proc$, F a HM formula)

$p \models tt$ for each $p \in Proc$

$p \models ff$ for no p (we also write $p \not\models ff$)

$p \models F \wedge G$ iff $p \models F$ and $p \models G$

$p \models F \vee G$ iff $p \models F$ or $p \models G$

$p \models \langle a \rangle F$ iff $p \xrightarrow{a} p'$ for some $p' \in Proc$ such that $p' \models F$

$p \models [a]F$ iff $p' \models F$, for all $p' \in Proc$ such that $p \xrightarrow{a} p'$

We write:

- $p \not\models F$ if p does not satisfy F
- $\langle \{a_1, a_2, \dots, a_n\} \rangle F$ for $\langle a_1 \rangle F \vee \langle a_2 \rangle F \dots \vee \langle a_n \rangle F$
- $[\{a_1, a_2, \dots, a_n\}] F$ for $[a_1] F \wedge [a_2] F \dots \wedge [a_n] F$

An Alternative (and Equivalent) Characterisation

Let $(Proc, Act, \{\xrightarrow{a} \mid a \in Act\})$ be an LTS.

Denotational Semantics

Let $\llbracket F \rrbracket \in Proc$, with F an HM formula, be defined by

$$\begin{aligned}\llbracket tt \rrbracket &= Proc, & \llbracket F \vee G \rrbracket &= \llbracket F \rrbracket \cup \llbracket G \rrbracket, \\ \llbracket ff \rrbracket &= \emptyset, & \llbracket \langle a \rangle F \rrbracket &= \langle \cdot a \cdot \rangle \llbracket F \rrbracket, \\ \llbracket F \wedge G \rrbracket &= \llbracket F \rrbracket \cap \llbracket G \rrbracket, & \llbracket [a] F \rrbracket &= [\cdot a \cdot] \llbracket F \rrbracket,\end{aligned}$$

where the operators $\langle \cdot a \cdot \rangle, [\cdot a \cdot] : 2^{Proc} \longrightarrow 2^{Proc}$ are defined by

$$\begin{aligned}\langle \cdot a \cdot \rangle S &= \{p \in Proc \mid p \xrightarrow{a} p' \text{ and } p' \in S \text{ for some } p'\}, \\ [\cdot a \cdot] S &= \{p \in Proc \mid p \xrightarrow{a} p' \text{ implies } p' \in S \text{ for each } p'\}.\end{aligned}$$

We write $p \models F$ iff $p \in \llbracket F \rrbracket$.

Examples

- $E \models \langle tick \rangle tt$
E can do a tick
- $E \models \langle tick \rangle \langle tock \rangle tt$
E can do a tick and then a tock
- $E \models \langle \{ tick, tock \} \rangle tt$
E can do a tick **or** a tock
- $E \models [tick] ff$
E cannot do a tick
- $E \models \langle tick \rangle ff$
This is equivalent to false!
- $E \models [tick] tt$
This is equivalent to true!

Checking Satisfaction

$$C \triangleq \text{tick}.C$$

Does C satisfy property $[\text{tick}](\langle \text{tick} \rangle tt \wedge [\text{tock}]ff)$?

Logical Negation

For every formula F we define the formula F^c as follows:

- $tt^c = ff$
- $ff^c = tt$
- $(F \wedge G)^c = F^c \vee G^c$
- $(F \vee G)^c = F^c \wedge G^c$
- $(\langle a \rangle F)^c = [a]F^c$. For instance $(\langle a \rangle tt)^c = [a]ff$
- $([a]F)^c = \langle a \rangle F^c$. For instance $([a]ff)^c = \langle a \rangle tt$

Theorem (F^c is equivalent to the negation of F)

For any $p \in Proc$ and any HML formula F

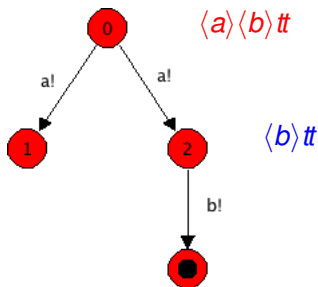
- 1 $p \models F \implies p \not\models F^c$
- 2 $p \not\models F \implies p \models F^c$

Checking Validity of HML Formulae

- 1 Decompose the HML formula into all its subformulas
- 2 Starting with the smallest subformula, label all states of the LTS where it holds
- 3 Repeat the previous step for the smallest remaining formula
- 4 If the state is labeled with the formula to be checked the formula is valid that state, otherwise, it is invalid.

Examples of Model Checking

Does the transition system corresponding to $a.0 + a.b.0$ satisfy the formula $\langle a \rangle \langle b \rangle tt$



Subformulae of $\langle a \rangle \langle b \rangle tt$:

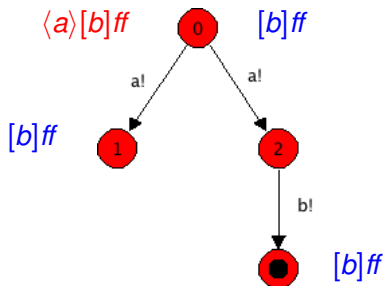
tt

$\langle b \rangle tt$

$\langle a \rangle \langle b \rangle tt$

Examples of Model Checking

Does the transition system corresponding to $a.0 + a.b.0$ satisfy formula $\langle a \rangle [b]ff$



Subformulae of $\langle a \rangle [b]ff$:

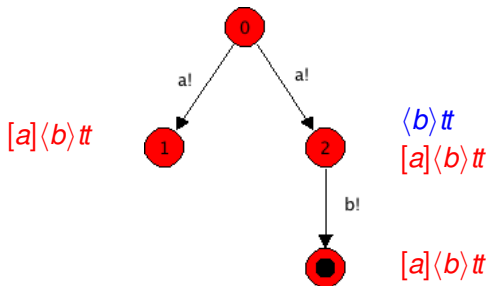
ff

$[b]ff$

$\langle a \rangle [b]ff$

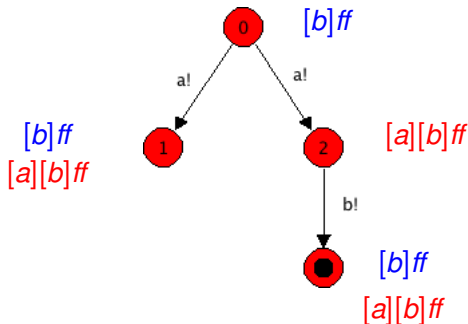
Examples of Model Checking

Does the transition system corresponding to $a.0 + a.b.0$ satisfy formula $[a]\langle b \rangle tt$



Examples of Model Checking

Does the transition system corresponding to $a.0 + a.b.0$ satisfy formula $[a][b]ff$



Examples

- $a.(b.0 + c.0) \models \langle a \rangle (\langle b \rangle tt \wedge \langle c \rangle tt)$
- $a.b.0 + a.c.0 \not\models \langle a \rangle (\langle b \rangle tt \wedge \langle c \rangle tt)$
- $a.b.0 \models [a] \langle b \rangle tt$
- $a.b.0 + a.0 \not\models [a] \langle b \rangle tt$
- $a.b.(c.0 + d.0) \models [a] \langle b \rangle \langle c \rangle tt$
- $a.b.c.0 + a.b.d.0 \not\models [a] \langle b \rangle \langle c \rangle tt$
- $a.(b.c.0 + b.d.0) \models [a] (\langle b \rangle \langle c \rangle tt \wedge \langle b \rangle \langle d \rangle tt)$
- $a.b.c.0 + a.b.d.0 \not\models [a] (\langle b \rangle \langle c \rangle tt \wedge \langle b \rangle \langle d \rangle tt)$

Theorem

$P \sim Q$ if and only $P \models F$ if and only if $Q \models F$ for every HML formula F .

Proof

(\implies) Proceeds by induction on F . The interesting case is $[a]F$.

(\impliedby) We show that the set \mathcal{S} of all pair of processes that satisfy the same HML formulae is a bisimulation. Suppose \mathcal{S} is not a bisimulation. Then, there exists a pair $\langle P, Q \rangle \in \mathcal{S}$ such that Q cannot match a move $P \xrightarrow{a} P'$. There are two cases.

Case 1: Q does not have a transition $Q \xrightarrow{a} Q'$, but then clearly P and Q do not satisfy the same formulae.

Case 2: for every evolution of $Q \xrightarrow{a} Q'$, Q' and P' do not satisfy the same formulae. Then, it is possible to construct a formula (of the form $\langle a \rangle F$ with $F = F_1 \wedge \dots \wedge F_n$) that P satisfies but Q does not.