

# Formal Techniques for Software Engineering: More on Denotational Semantics

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Lesson 5

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# Syntax and Semantics

## Syntax

Set of rules for defining "well formed phrases"

## Syntactic Domain

Set of well formed phrases

## Semantic Domain

Set of known entities

## Semantic Interpretation

Mapping from Syntactic Domain to Semantic Domain or Interpretation of well formed phrases in terms of known concepts

# Tiny: A simple imperative language

## Syntax

$$\begin{aligned} e & ::= \text{true} \mid \text{false} \mid \text{not } e \mid n \mid e_1 \text{ nop } e_2 \mid e_1 \text{ bop } e_2 \mid \text{read} \mid x \\ c & ::= \text{noaction} \mid x := e \mid c_1; c_2 \mid \text{if } e \text{ then } c_1 \text{ else } c_2 \mid \\ & \quad \mid \text{while } e \text{ do } c \mid \text{output } e \end{aligned}$$

- *Exp* denotes the set of expressions generable by the above grammar starting from *e*
- *Com* denotes the set of commands generable by the above grammar starting from *c*

# Tiny: A simple imperative language

## Syntax

```
e ::= true | false | not e | n | e1 nop e2 | e1 bop e2 | read | x  
c ::= noaction | x := e | c1; c2 | if e then c1 else c2 |  
| while e do c | output e
```

- $Exp$  denotes the set of expressions generable by the above grammar starting from  $e$
- $Com$  denotes the set of commands generable by the above grammar starting from  $c$

## Transition System for Expressions

The transition system for expressions is:  $(\Sigma, \Sigma_F, \longrightarrow)$

- $\Sigma = \{\langle e, \sigma \rangle \mid e \in Exp, \sigma : \text{Id} \rightarrow \text{Val}\} \cup \{\sigma : \text{Id} \rightarrow \text{Val}\}$
- $\Sigma_F = \{\sigma : \text{Id} \rightarrow \text{Val}\}$

# Tiny: A simple imperative language

## Syntax

```
e ::= true | false | not e | n | e1 nop e2 | e1 bop e2 | read | x  
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- $Exp$  denotes the set of expressions generable by the above grammar starting from  $e$
- $Com$  denotes the set of commands generable by the above grammar starting from  $c$

## Transition System for Commands

The transition system for commands is:  $(K, K_F, \rightarrow)$

- $K = \{\langle c, \sigma \rangle \mid c \in Com, \sigma : Id \rightarrow Val\}$
- $K_F = \{\langle noaction, \sigma \rangle \mid \sigma : Id \rightarrow Val\}$

# Notation

## State update

Given state  $\sigma$ , value  $v \in \text{Val}$ , identifier  $id \in \text{Id}$ ,

$$\begin{aligned}\sigma[v/id](id') &= \sigma(id') \quad \text{if } id' \neq id, \\ &= v \quad \quad \quad \text{otherwise.}\end{aligned}$$

Before it was  $\sigma\{v \mapsto id\}$

## Special identifiers

- **res**: will denote a basic (boolean or natural) value
- **in**: will denote a sequence of basic values - **inputs**
- **out**: will denote a sequence of basic values - **outputs**
  - **Results** of a function evaluations are associated to **res**.
  - **read** extracts a value from **in** and stores them in **res**
  - **output** adds values to **out**

# Operational Semantics of Expressions

$$\langle \mathbf{true}, \sigma \rangle \longrightarrow \sigma[\mathit{true}/\text{res}] \quad (\text{True})$$

$$\langle \mathbf{false}, \sigma \rangle \longrightarrow \sigma[\mathit{false}/\text{res}] \quad (\text{False})$$

$$\langle n, \sigma \rangle \longrightarrow \sigma[n/\text{res}] \quad (\text{Nat})$$

$$\langle x, \sigma \rangle \longrightarrow \sigma[\sigma(x)/\text{res}] \quad (\text{Ide})$$

$$\frac{\langle e, \sigma \rangle \longrightarrow \sigma' \quad \sigma'(\text{res}) = v}{\langle \mathbf{not} \, e, \sigma \rangle \longrightarrow \sigma'[\neg v/\text{res}]} \quad (\text{Not})$$

$$\frac{\begin{array}{c} \langle e_1, \sigma \rangle \longrightarrow \sigma' \quad \sigma'(\text{res}) = v_1 \\ \langle e_2, \sigma' \rangle \longrightarrow \sigma'' \quad \sigma''(\text{res}) = v_2 \end{array}}{\langle e_1 \, \mathit{bop} \, e_2, \sigma \rangle \longrightarrow \sigma''[v_1 \, \mathit{bop} \, v_2/\text{res}]} \quad (\text{Bop})$$

$$\frac{\begin{array}{c} \langle e_1, \sigma \rangle \longrightarrow \sigma' \quad \sigma'(\text{res}) = v_1 \\ \langle e_2, \sigma' \rangle \longrightarrow \sigma'' \quad \sigma''(\text{res}) = v_2 \end{array}}{\langle e_1 \, \mathit{nop} \, e_2, \sigma \rangle \longrightarrow \sigma''[v_1 \, \mathit{nop} \, v_2/\text{res}]} \quad (\text{Nop})$$

$$\langle \mathbf{read}, \sigma \rangle \longrightarrow \sigma[\mathit{hd}(\sigma(\text{in}))/\text{res}, \mathit{tl}(\sigma(\text{in}))/\text{in}] \quad (\text{Read})$$

# Operational Semantics of Commands

$$\frac{\langle e, \sigma \rangle \longrightarrow \sigma' \quad \sigma'(\text{res}) = v}{\langle x := e, \sigma \rangle \longrightarrow \langle \text{noaction}, \sigma'[v/x] \rangle} \text{ (Ass)}$$

$$\langle \text{noaction}; c_2, \sigma \rangle \longrightarrow \langle c_2, \sigma \rangle \text{ (Seq}_1\text{)}$$

$$\frac{\langle c_1, \sigma \rangle \longrightarrow \langle c'_1, \sigma' \rangle}{\langle c_1; c_2, \sigma \rangle \longrightarrow \langle c'_1; c_2, \sigma' \rangle} \text{ (Seq}_2\text{)}$$

$$\frac{\langle e, \sigma \rangle \longrightarrow \sigma' \quad \sigma'(\text{res}) = \text{true}}{\langle \text{if } e \text{ then } c_1 \text{ else } c_2, \sigma \rangle \longrightarrow \langle c_1, \sigma' \rangle} \text{ (Cond}_1\text{)}$$

$$\frac{\langle e, \sigma \rangle \longrightarrow \sigma' \quad \sigma'(\text{res}) = \text{false}}{\langle \text{if } e \text{ then } c_1 \text{ else } c_2, \sigma \rangle \longrightarrow \langle c_2, \sigma' \rangle} \text{ (Cond}_2\text{)}$$

$$\frac{\langle e, \sigma \rangle \longrightarrow \sigma' \quad \sigma'(\text{res}) = \text{true}}{\langle \text{while } e \text{ do } c, \sigma \rangle \longrightarrow \langle c; \text{while } e \text{ do } c, \sigma' \rangle} \text{ (While}_1\text{)}$$

$$\frac{\langle e, \sigma \rangle \longrightarrow \sigma' \quad \sigma'(\text{res}) = \text{false}}{\langle \text{while } e \text{ do } c, \sigma \rangle \longrightarrow \langle \text{noaction}, \sigma' \rangle} \text{ (While}_2\text{)}$$

$$\frac{\langle e, \sigma \rangle \longrightarrow \sigma' \quad \sigma'(\text{res}) = v}{\langle \text{output } e, \sigma \rangle \longrightarrow \langle \text{noaction}, \sigma'[v :: (\sigma(\text{out}))/\text{out}] \rangle} \text{ (Out)}$$

# Domains for Denotational Semantics

## Semantic Domains

To specify the interpretation functions  $\mathcal{E}$  and  $\mathcal{C}$  for  $Exp$  and  $Com$  we need to specify their semantic domain  $\mathbb{D}_1 \in \mathbb{D}_2$ :

$$\begin{aligned}\mathcal{E} : Exp &\longrightarrow \mathbb{D}_1 \\ \mathcal{C} : Com &\longrightarrow \mathbb{D}_2.\end{aligned}$$

We make use of

$$\begin{aligned}\text{VAL} &= \text{NAT} + \text{BOOL} \\ \text{MEM} &= \text{ID} \longrightarrow (\text{VAL} + \{\text{unbound}\}) \\ \text{STATE} &= \text{VAL}^* \times \text{VAL}^* \times \text{MEM}.\end{aligned}$$

## Semantic Domains

$$\mathcal{E} : Exp \longrightarrow \text{STATE} \longrightarrow ((\text{VAL} \times \text{STATE}) + \{\text{error}\})$$

$$\mathcal{C} : Com \longrightarrow \text{STATE} \longrightarrow (\text{STATE} + \{\text{error}\})$$

# Auxiliary notation

## *let* and *cond* construct

We shall use

- *let x be e<sub>1</sub> in e<sub>2</sub>* instead of  $(\lambda x. e_2) e_1$ .
- $e \rightarrow e_1, e_2$  instead of *cond(e, e<sub>1</sub>, e<sub>2</sub>)*

## *cases* construct

If  $p_i(\cdot)$  is a predicate selecting  $e_i$  according to the properties (type, value, structure) of  $e$ , we use

*cases e of*  
 $p_1(e) : e_1$   
 $p_2(e) : e_2$   
...  
 $p_n(e) : e_n$

*endcases*

instead of

*let x be e in*

$p_1(x) \rightarrow e'_1, (p_2(x) \rightarrow e'_2, (\dots (p_n(x) \rightarrow e'_n) \dots))$

# Denotational Semantics of TINY Expressions

$$\mathcal{E}[\text{true}] = \lambda\sigma. \langle \text{true}, \sigma \rangle$$

$$\mathcal{E}[\text{false}] = \lambda\sigma. \langle \text{false}, \sigma \rangle$$

$$\mathcal{E}[n] = \lambda\sigma. \langle n, \sigma \rangle$$

$$\mathcal{E}[\text{read}] = \lambda(in, out, mem). \langle hd(in), \langle tl(in), out, mem \rangle \rangle$$

$$\mathcal{E}[\text{not } e] = \lambda\sigma. \langle \neg\pi_1(\mathcal{E}[e]\sigma), \pi_2(\mathcal{E}[e]\sigma) \rangle$$

$$\mathcal{E}[e_1 \text{ nop } e_2] =$$

$$\lambda\sigma. \left\langle \pi_1(\mathcal{E}[e_1]\sigma) \text{ nop } \pi_1\left(\mathcal{E}[e_2](\pi_2(\mathcal{E}[e_1]\sigma))\right), \pi_2\left(\mathcal{E}[e_2](\pi_2(\mathcal{E}[e_1]\sigma))\right) \right\rangle$$

$$\mathcal{E}[e_1 \text{ bop } e_2] = \lambda\sigma. \text{let } (\mathcal{E}[e_1]\sigma) \text{ be}$$

$$\quad \quad \quad \langle v_1, \sigma_1 \rangle \text{ in let } (\mathcal{E}[e_2]\sigma_1) \text{ be}$$

$$\quad \quad \quad \langle v_2, \sigma_2 \rangle \text{ in } \langle v_1 \text{ bop } v_2, \sigma_2 \rangle$$

$$\mathcal{E}[x] = \lambda(in, out, mem). \text{mem}(x) = \text{unbound} \rightarrow \text{error},$$

$$\quad \quad \quad \langle \text{mem}(x), \langle in, out, mem \rangle \rangle$$

# Denotational Semantics of TINY Commands

$$\mathcal{C}[\text{noaction}] = \lambda\sigma. \sigma$$

$$\mathcal{C}[x := e] = \lambda\sigma. < \pi_1(\pi_2(\mathcal{E}[e]\sigma)), \pi_2(\sigma), \pi_3(\sigma)[\pi_1(\mathcal{E}[e]\sigma)/x] >$$

$$\mathcal{C}[c_1; c_2] = \lambda\sigma. \mathcal{C}[c_2](\mathcal{C}[c_1]\sigma);$$

$$\begin{aligned}\mathcal{C}[\text{if } e \text{ then } c_1 \text{ else } c_2] = \lambda\sigma. \text{let } (\mathcal{E}[e]\sigma) \text{ be } &< v, \sigma' > \text{ in} \\ &v \rightarrow \mathcal{C}[c_1]\sigma', \mathcal{C}[c_2]\sigma'\end{aligned}$$

$$\begin{aligned}\mathcal{C}[\text{output } e] = \lambda\sigma. \text{let } (\mathcal{E}[e]\sigma) \text{ be } &< v, < \text{in}, \text{out}, \text{mem} > > \text{ in} \\ &< \text{in}, v :: \text{out}, \text{mem} >\end{aligned}$$

$$\begin{aligned}\mathcal{C}[\text{while } e \text{ do } c] = \text{fix} \left( \lambda \Theta_w. \lambda\sigma. \text{let } (\mathcal{E}[e]\sigma) \text{ be } &< v, \sigma' > \text{ in} \\ &v \rightarrow \Theta_w(\mathcal{C}[c]\sigma'), \sigma' \right)\end{aligned}$$

Why the latter?

# Denotational Semantics of **while**

**while e do c**  $\approx$  **if e then ( c; while e do c ) else noaction**

By considering the semantics of **if**, we have:

$$\begin{aligned} \mathcal{C}[\text{while } e \text{ do } c] &= \lambda\sigma. \text{let } (\mathcal{E}[e]\sigma) \text{ be } <\nu, \sigma'> \text{ in} \\ &\quad \nu \rightarrow \mathcal{C}[c; \text{while } e \text{ do } c]\sigma', \mathcal{C}[\text{noaction}]\sigma' \end{aligned}$$

By considering the semantics of ; and **noaction**, we have:

$$\begin{aligned} \mathcal{C}[\text{while } e \text{ do } c] &= \lambda\sigma. \text{let } (\mathcal{E}[e]\sigma) \text{ be } <\nu, \sigma'> \text{ in} \\ &\quad \nu \rightarrow \mathcal{C}[\text{while } e \text{ do } c](\mathcal{C}[c]\sigma'), \mathcal{C}[\text{noaction}]\sigma' \\ \mathcal{C}[\text{while } e \text{ do } c] &= \Theta_w = \lambda\sigma. \text{let } (\mathcal{E}[e]\sigma) \text{ be } <\nu, \sigma'> \text{ in} \\ &\quad \nu \rightarrow \Theta_w(\mathcal{C}[c]\sigma'), \sigma' \end{aligned}$$

By abstracting on  $\Theta_w$  we have a recursive function for which we can calculate the **fixed point**:

$$\begin{aligned} \mathcal{C}[\text{while } e \text{ do } c] &= \\ &\quad \lambda\Theta_w. \lambda\sigma. \text{let } (\mathcal{E}[e]\sigma) \text{ be } <\nu, \sigma'> \text{ in } \nu \rightarrow \Theta_w(\mathcal{C}[c]\sigma'), \sigma' \end{aligned}$$

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# A richer language

## Syntax for SMALL

```
prog ::= program c
d     ::= const x = e | var x = e | proc p(x); c | fun f(x); e | d1; d2
e     ::= b | n | not e | e1 nop e2 | e1 bop e2
          | if e then e1 else e2 | x | e(e1) | read
c     ::= e := e1 | c1; c2 | if e then c1 else c2 | while e do c |
          | output e | begin d; c end | e(e1)
```

## New Ingredients

- Blocks for variable scoping
- Procedure Calls
- Function Calls
- No noaction

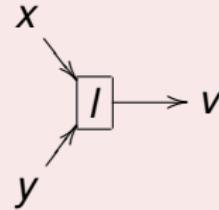
# Blocks and Variables in SMALL

## An Example SMALL Program

```
program
begin
  var x = 100;
  var y = 0;
  y := x;
  begin
    var x = 1;
    y := x
  end;
  y := x
end
```

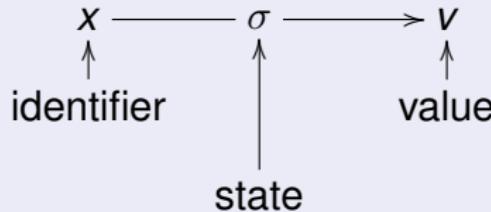
## Scopes of variables

- A variable can have different values depending on the block in which it is declared
- Two variables can refer to the same location (**aliasing**) and take always the same value.

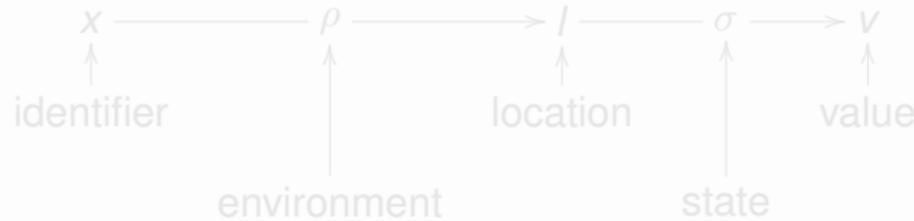


# Variables binding

## Binding in TINY

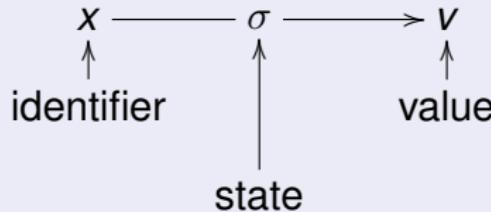


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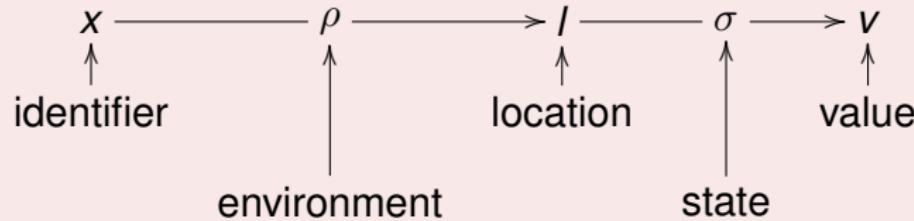


# Variables binding

## Binding in TINY



## Binding in SMALL



# Semantic Domains

## Values

- BVAL** **Basic Values**: can be input or output of Programs (e.g. naturals and booleans).
- NVAL** **Nameable Values** can be denoted by an identifier (e.g. locations or procedures).
- EVAL** **Expressible Values**: the set of values that expression can take (e.g. functions or basic values)
- SVAL** **Storable Values**: the set of values associated to memory locations (e.g. basic values or sequences thereof)

## Semantic Domains for SMALL

$$\text{BVAL} = \text{NAT} + \text{BOOL}$$

$$\text{NVAL} = \text{BVAL} + \text{LOC} + \text{FUN} + \text{PROC}$$

$$\text{EVAL} = \text{NVAL}$$

$$\text{SVAL} = \text{BVAL} + \text{BVAL}^*$$

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## Semantic Domains for SMALL

$$\text{BVAL} = \text{NAT} + \text{BOOL}$$

$$\text{NVAL} = \text{BVAL} + \text{LOC} + \text{FUN} + \text{PROC}$$

$$\text{EVAL} = \text{NVAL}$$

$$\text{SVAL} = \text{BVAL} + \text{BVAL}^*$$

# Stores and Environments

## Domains for Environment and Stores

$$\text{ENV} = \text{ID} \longrightarrow (\text{NVAL} + \{\text{unbound}\})$$

$$\text{STORE} = \text{LOC} \longrightarrow (\text{SVAL} + \{\text{unused}\})$$

## Updates for Stores and Environment

- ①  $\rho[\text{loc}/\text{id}]$  stands for  $\lambda x. (x = \text{id}) \rightarrow \text{loc}, \rho(x)$ ;
- ②  $\rho[\rho']$  stands for  $\lambda x. (\rho'(x) = \text{unbound}) \rightarrow \rho(x), \rho'(x)$ .
- ③  $\sigma[\text{val}/\text{loc}]$  stands for  $\lambda x. (x = \text{loc}) \rightarrow \text{val}, \sigma(x)$ .

## Generating new locations

To refer to a new location we use

$$\text{new} : \text{STORE} \longrightarrow \text{LOC}$$

that applied to state  $\sigma$  returns the smallest  $n$  that has never been used, e.g.,  $n$  such that  $\sigma(n) = \text{unused}$  and  $\sigma(m) \neq \text{unused}, \forall m < n$ .

# Semantic Interpretation Function

## Programs

$$\mathcal{P} : \text{Prog} \longrightarrow \text{BVAL}^* \longrightarrow (\text{BVAL}^* + \{\text{error}\})$$

## Declarations

$$\mathcal{D} : \text{Dec} \longrightarrow \text{ENV} \longrightarrow \text{STORE} \longrightarrow ((\text{ENV} \times \text{STORE}) + \{\text{error}\})$$

## Expressions

$$\mathcal{E} : \text{Exp} \longrightarrow \text{ENV} \longrightarrow \text{STORE} \longrightarrow ((\text{EVAL} \times \text{STORE}) + \{\text{error}\})$$

$$\mathcal{R} : \text{Exp} \longrightarrow \text{ENV} \longrightarrow \text{STORE} \longrightarrow ((\text{BVAL} \times \text{STORE}) + \{\text{error}\})$$

## Commands

$$\mathcal{C} : \text{Com} \longrightarrow \text{ENV} \longrightarrow \text{STORE} \longrightarrow (\text{STORE} + \{\text{error}\})$$

# Auxiliary Operators

## An operator for error handling

① If  $f : D_1 \rightarrow (D_2 + \{\text{error}\})$  and  $g : D_2 \rightarrow (D_3 + \{\text{error}\})$ , then

$$f \star g : D_1 \rightarrow (D_3 + \{\text{error}\})$$

$$f \star g = \lambda x. f x = \text{error} \rightarrow \text{error}, g(fx).$$

② If  $f : D_1 \rightarrow ((D_2 \times D_3) + \{\text{error}\})$  and

$$g : D_2 \rightarrow D_3 \rightarrow (D_4 + \{\text{error}\}) \text{ then}$$

$$f \star g : D_1 \rightarrow (D_4 + \{\text{error}\})$$

$$\begin{aligned} f \star g = \lambda x. & \text{cases } f x \text{ of} \\ & < d_1, d_2 > : g d_1 d_2; \\ & \text{error} : \text{error} \\ & \text{endcases} \end{aligned}$$

# Auxiliary Operators

## Using $\star$

If we would have considered errors, the full semantics of ; in TINY would have been:

$$\begin{aligned}\mathcal{C}[\![c_1; c_2]\!] = & \lambda\sigma. \text{cases } \mathcal{C}[\![c_1]\!] \sigma \text{ of} \\ & \sigma' : \mathcal{C}[\![c_2]\!] \sigma'; \\ & \text{error} : \text{error} \\ & \text{endcases}\end{aligned}$$

with the  $\star$  operator, it becomes:

$$\mathcal{C}[\![c_1; c_2]\!] = \mathcal{C}[\![c_1]\!] \star \mathcal{C}[\![c_2]\!].$$

# Auxiliary Operators

Checking types of results

$$\text{check}D = \lambda v. \lambda \sigma. \text{is}D(v) \rightarrow < v, \sigma >, \text{error}.$$

*check*D acts as a filter between two functions. It transmits only the result of the first function to the second one only if it is of type D.

By using  $\star$  and *check*D we have that the semantics of **not** in TINY, that when taking errors into account would have been:

$$\begin{aligned}\mathcal{E}[\![\text{not } e]\!] &= \lambda \sigma. \text{cases } \mathcal{E}[\![e]\!] \sigma \text{ of} \\ &\quad < v, \sigma' >: \text{isbool}(v) \rightarrow < \neg v, \sigma' >, \text{error}; \\ &\quad \text{error} : \text{error} \\ &\quad \text{endcases}\end{aligned}$$

becomes:

$$\mathcal{E}[\![\text{not } e]\!] = \mathcal{E}[\![e]\!] \star \text{checkBOOL} \star \lambda v \sigma. < \neg v, \sigma >$$

# Denotational Semantics of SMALL

## Semantics of Programs

$$\mathcal{P} : \text{Prog} \longrightarrow \text{BVAL}^* \longrightarrow (\text{BVAL}^* + \{\text{error}\})$$

$\mathcal{P}[\![\text{program } c]\!]_{in} = \text{cases } \mathcal{C}[c]_{\rho_0}(\lambda x. \text{unused})[in/lin][nil/lout] \text{ of}$   
 $\sigma : \sigma(lout);$   
 $\text{error} : \text{error}$   
 $\text{endcases}$

## Semantics of Declarations

$$\mathcal{D} : \text{Dec} \longrightarrow \text{ENV} \longrightarrow \text{STORE} \longrightarrow ((\text{ENV} \times \text{STORE}) + \{\text{error}\})$$

$\mathcal{D}[\![\text{const } x = e]\!] \rho = \mathcal{R}[e] \rho \star \lambda v \sigma. < \rho_0[v/x], \sigma >$

$\mathcal{D}[\![\text{var } x = e]\!] \rho = \mathcal{R}[e] \rho \star \lambda v \sigma. < \rho_0[\text{new } \sigma/x], \sigma[v/\text{new } \sigma] >$

$\mathcal{D}[\![\text{proc } p(x); c]\!] \rho = \lambda \sigma. < \rho_0[(\lambda d. \mathcal{C}[c] \rho[d/x])/p], \sigma >$

$\mathcal{D}[\![\text{fun } f(x); e]\!] \rho = \lambda \sigma. < \rho_0[(\lambda d. \mathcal{E}[e] \rho[d/x])/f], \sigma >$

# Denotational Semantics of SMALL

## Semantics of Programs

$$\mathcal{P} : \text{Prog} \longrightarrow \text{BVAL}^* \longrightarrow (\text{BVAL}^* + \{\text{error}\})$$

$\mathcal{P}[\![\text{program } c]\!]_{in} = \text{cases } \mathcal{C}[c]_{\rho_0}(\lambda x. \text{unused})[in/lin][nil/lout] \text{ of}$   
 $\sigma : \sigma(lout);$   
 $\text{error} : \text{error}$   
 $\text{endcases}$

## Semantics of Declarations

$$\mathcal{D} : \text{Dec} \longrightarrow \text{ENV} \longrightarrow \text{STORE} \longrightarrow ((\text{ENV} \times \text{STORE}) + \{\text{error}\})$$

$\mathcal{D}[\![\text{const } x = e]\!] \rho = \mathcal{R}[e] \rho \star \lambda v \sigma. < \rho_0[v/x], \sigma >$

$\mathcal{D}[\![\text{var } x = e]\!] \rho = \mathcal{R}[e] \rho \star \lambda v \sigma. < \rho_0[\text{new } \sigma/x], \sigma[v/\text{new } \sigma] >$

$\mathcal{D}[\![\text{proc } p(x); c]\!] \rho = \lambda \sigma. < \rho_0[(\lambda d. \mathcal{C}[c] \rho[d/x])/p], \sigma >$

$\mathcal{D}[\![\text{fun } f(x); e]\!] \rho = \lambda \sigma. < \rho_0[(\lambda d. \mathcal{E}[e] \rho[d/x])/f], \sigma >$

# Functions and Procedures

## Types

$$\text{FUN} = \text{NVAL} \longrightarrow \text{STORE} \longrightarrow ((\text{EVAL} \times \text{STORE}) + \{\text{error}\})$$
$$\text{PROC} = \text{NVAL} \longrightarrow \text{STORE} \longrightarrow (\text{STORE} + \{\text{error}\})$$

## Declarations

$$\mathcal{D}[\![\text{proc } p(x); c]\!] \rho = \lambda\sigma. < \rho_0[(\lambda d. \mathcal{C}[\![c]\!] \rho[d/x])/p], \sigma >$$
$$\mathcal{D}[\![\text{fun } f(x); e]\!] \rho = \lambda\sigma. < \rho_0[(\lambda d. \mathcal{E}[\![e]\!] \rho[d/x])/f], \sigma >$$

## Invocations

$$\mathcal{E}[\![e(e')]\!] \rho = \mathcal{E}[\![e]\!] \rho \star \text{checkFUN} \star \lambda f. \mathcal{E}[\![e']]\! \rho \star \lambda v. \lambda\sigma. f \nu \sigma$$
$$\mathcal{C}[\![e(e')]\!] \rho = \mathcal{E}[\![e]\!] \rho \star \text{checkPROC} \star \lambda p. \mathcal{E}[\![e']]\! \rho \star \lambda v \sigma. p \nu \sigma$$

# Denotational Semantics of Expressions

## Another auxiliary operator

To avoid explicitly **dereferencing** the result of the evaluation of an expression when this yields a location -  $\sigma(\mathcal{E}[e])$ -, a new valuation function for expressions  $\mathcal{R}$  is introduced that is similar to  $\mathcal{E}$ , but yields *error* when  $\mathcal{E}[e]$  is not a basic value or a location.

$$\mathcal{R} : \textit{Exp} \longrightarrow \text{ENV} \longrightarrow \text{STORE} \longrightarrow (\text{BVAL} \times \text{STORE}) + \{\text{error}\}$$

$$\begin{aligned}\mathcal{R}[e]\rho = \mathcal{E}[e]\rho &\star \lambda v\sigma. \text{cases } v \text{ of} \\ &\quad \text{isbval}(v) : < v, \sigma >; \\ &\quad \text{isloc}(v) : \sigma(v) = \text{unused} \rightarrow \text{error}, \\ &\quad \qquad \qquad \qquad < \sigma(v), \sigma >; \\ &\quad \text{isfun}(v) : \text{error}; \\ &\quad \text{isproc}(v) : \text{error} \\ &\text{endcases}\end{aligned}$$

# Semantics of Expressions

$$\mathcal{E} : \textit{Exp} \longrightarrow \text{ENV} \longrightarrow \text{STORE} \longrightarrow ((\text{EVAL} \times \text{STORE}) + \{\text{error}\})$$

## Constants

$$\mathcal{E}[\text{true}] \rho = \lambda\sigma. \langle \text{true}, \sigma \rangle$$

$$\mathcal{E}[\text{false}] \rho = \lambda\sigma. \langle \text{false}, \sigma \rangle$$

$$\mathcal{E}[n] \rho = \lambda\sigma. \langle n, \sigma \rangle$$

## Basic Operations

$$\mathcal{E}[\text{not } e] \rho = \mathcal{R}[e] \rho \star \text{checkBOOL} \star \lambda b \sigma. \langle \neg b, \sigma \rangle$$

$$\begin{aligned} \mathcal{E}[e_1 \text{ nop } e_2] \rho &= \mathcal{R}[e_1] \rho \star \text{checkNAT} \\ &\quad \star \lambda n_1. \mathcal{R}[e_2] \rho \star \text{checkNAT} \star \lambda n_2 \sigma. \langle n_1 \text{ nop } n_2, \sigma \rangle \end{aligned}$$

$$\begin{aligned} \mathcal{E}[e_1 \text{ bop } e_2] \rho &= \mathcal{R}[e_1] \rho \star \text{checkBOOL} \\ &\quad \star \lambda b_1. \mathcal{R}[e_2] \rho \star \text{checkBOOL} \star \lambda b_2 \sigma. \langle b_1 \text{ bop } b_2, \sigma \rangle \end{aligned}$$

# Semantics of Expressions

## Conditional expressions

$$\mathcal{E}[\text{if } e \text{ then } e_1 \text{ else } e_2] \rho = \mathcal{R}[e] \rho * \text{checkBOOL} \\ * \lambda b. b \rightarrow \mathcal{E}[e_1] \rho, \mathcal{E}[e_2] \rho$$

## Input expressions

$$\mathcal{E}[\text{read}] \rho = \lambda \sigma. \text{cases } \sigma(\text{lin}) \text{ of} \\ v :: \text{in} : < v, \sigma[\text{in}/\text{lin}] >; \\ \text{nil} : \text{error} \\ \text{endcases}$$

## Variables interpretation

$$\mathcal{E}[x] \rho = \lambda \sigma. \rho(x) = \text{unbound} \rightarrow \text{error}, < \rho(x), \sigma >$$

## Function calls

$$\mathcal{E}[e(e')] \rho = \mathcal{E}[e] \rho * \text{checkFUN} * \lambda f. \mathcal{E}[e'] \rho * \lambda v. \lambda \sigma. f v \sigma$$

# Semantics of expressions

$$\text{FUN} = \text{NVAL} \longrightarrow \text{STORE} \longrightarrow ((\text{EVAL} \times \text{STORE}) + \{\text{error}\})$$

## Function Calls

$$\mathcal{E}[e(e')] \rho = \mathcal{E}[e] \rho * \text{checkFUN} * \lambda f. \mathcal{E}[e'] \rho * \lambda v. \lambda \sigma. f v \sigma$$

- ① To evaluate the argument we use  $\mathcal{E}$  and not  $\mathcal{R}$ , thus we can pass as argument any expressible value, i.e. not only basic values but also locations, procedures or one functions.
- ② The environment,  $\rho$ , used when calling the function is not used during the actual evaluation of the function. Here only the argument and the state are used. The environment that is used is the one active when the function was defined (**static scoping**)

## Function Declaration

$$\mathcal{D}[\text{fun } f(x); e] \rho = \lambda \sigma. < \rho_0[(\lambda d. \mathcal{E}[e] \rho[d/x]) / f], \sigma >$$

# Semantics of Commands

$$\mathcal{C} : \text{Com} \longrightarrow \text{ENV} \longrightarrow \text{STORE} \longrightarrow (\text{STORE} + \{\text{error}\})$$

$$\mathcal{C}[e := e'] \rho = \mathcal{E}[e] \rho \star \text{checkLOC} \star \lambda I. \mathcal{R}[e'] \rho \star \lambda v \sigma. \sigma[v/I]$$

$$\mathcal{C}[c_1; c_2] \rho = \mathcal{C}[c_1] \rho \star \mathcal{C}[c_2] \rho$$

$$\begin{aligned} \mathcal{C}[\text{if } e \text{ then } c_1 \text{ else } c_2] \rho &= \mathcal{R}[e] \rho \star \text{checkBOOL} \\ &\quad \star \lambda b. b \rightarrow \mathcal{C}[c_1] \rho, \mathcal{C}[c_2] \rho \end{aligned}$$

$$\begin{aligned} \mathcal{C}[\text{while } e \text{ do } c] \rho &= \text{fix}(\lambda \Theta. \mathcal{R}[e] \rho \star \text{checkBOOL} \\ &\quad \star \lambda b. b \rightarrow \mathcal{C}[c] \rho \star \Theta, \lambda \sigma. \sigma \end{aligned}$$

$$\mathcal{C}[\text{output } e] \rho = \mathcal{R}[e] \rho \star \lambda b \sigma. \sigma[b :: \sigma(lout)/lout]$$

$$\mathcal{C}[\text{begin } d; c \text{ end}] \rho = \mathcal{D}[d] \rho \star \lambda \rho'. \mathcal{C}[c] \rho[\rho']$$

$$\mathcal{C}[e(e')] \rho = \mathcal{E}[e] \rho \star \text{checkPROC} \star \lambda p. \mathcal{E}[e'] \rho \star \lambda v \sigma. p \vee \sigma$$